- 1. Anisotropic Gaussian Mutations for Metropolis Light Transport through Hessian-Hamiltonian Dynamics
- 2. Fusing State Spaces for Markov Chain Monte Carlo Rendering

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#### Overview

#### 1. Backgrounds

- Metropolis Algorithm
- Metropolis Light Transport
- Primary Sample Space MLT
- 2. Anisotropic Gaussian Mutations for Metropolis Light Transport through Hessian-Hamiltonian Dynamics
  - Introduction
  - Results
- 3. Fusing State Spaces for Markov Chain Monte Carlo Rendering
  - Introduction
  - Results

# Metropolis Algorithm [N. Metropolis '53, W. K. Hastings '70]

- One kind of Markov chain Monte Carlo methods.
- Generate samples of target probability distribution by sampling **arbitrary distribution**.

Metropolis Algorithm [N. Metropolis '53, W. K. Hastings '70]

Target r(x)/Z. Symmetric proposal q(x'|x).

- I. initialise  $x_1$  randomly; n:=I
- 2. repeat:
  - a)  $x' \sim q(x'|x_n); \quad \alpha := \min(1, r(x')/r(x_n))$
  - b)  $u \sim uniform(0,1)$
  - c)  $x_{n+1} := (if (u \le \alpha) \text{ then } x' \text{ else } x_n); n:=n+1$

- Metropolis Algorithm to compute light transport integral.
- **Mutation strategies** to avoid **variance** originated from sampling from proposal distribution.

The light transport equation

$$L(\mathbf{x}' \to \mathbf{x}'') = L_{e}(\mathbf{x}' \to \mathbf{x}'')$$

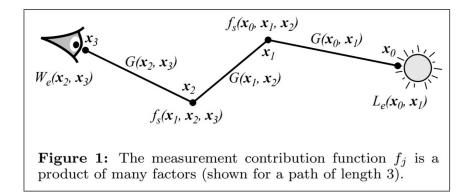
$$+ \int_{\mathcal{M}} L(\mathbf{x} \to \mathbf{x}') f_{s}(\mathbf{x} \to \mathbf{x}' \to \mathbf{x}'') G(\mathbf{x} \leftrightarrow \mathbf{x}') dA(\mathbf{x}).$$
(6)

$$G(\mathbf{x} \leftrightarrow \mathbf{x}') = V(\mathbf{x} \leftrightarrow \mathbf{x}') \frac{|\cos(\theta_{\rm o}) \cos(\theta_{\rm i}')|}{\|\mathbf{x} - \mathbf{x}'\|^2}$$

#### The measurement equation

$$m_{j} = \int_{\mathcal{M}^{2}} L_{e}(\mathbf{x}_{0} \to \mathbf{x}_{1}) G(\mathbf{x}_{0} \leftrightarrow \mathbf{x}_{1}) W_{e}^{(j)}(\mathbf{x}_{0} \to \mathbf{x}_{1}) dA(\mathbf{x}_{0}) dA(\mathbf{x}_{1}) + \int_{\mathcal{M}^{3}} L_{e}(\mathbf{x}_{0} \to \mathbf{x}_{1}) G(\mathbf{x}_{0} \leftrightarrow \mathbf{x}_{1}) f_{s}(\mathbf{x}_{0} \leftrightarrow \mathbf{x}_{1} \leftrightarrow \mathbf{x}_{2}) G(\mathbf{x}_{1} \leftrightarrow \mathbf{x}_{2}) W_{e}^{(j)}(\mathbf{x}_{1} \to \mathbf{x}_{2}) dA(\mathbf{x}_{0}) dA(\mathbf{x}_{1}) dA(\mathbf{x}_{2}) + \cdots$$
(8)

$$m_j = \int_{\Omega} f_j(\bar{x}) \ d\mu(\bar{x})$$



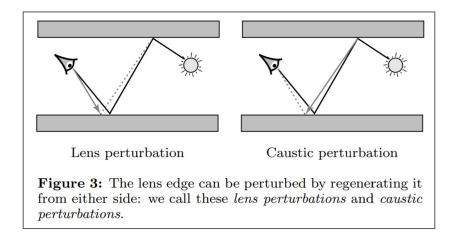
Goal: Estimate the expectation of the measurement with Monte Carlo

$$m_j = E\left[\frac{1}{N} \sum_{i=1}^N \frac{w_j(\bar{X}_i)f(\bar{X}_i)}{p(\bar{X}_i)}\right]$$

where 
$$p~=~(1/b)\,f$$

#### Metropolis algorithm in Metropolis Light Transport

- Sampling p = (1/b) f using **Metropolis algorithm**.
- Flexible to choose the proposal probability distribution (mutation).
- **Mutation** strategies: bidirectional mutations, perturbations, and lens subpath mutations.
- Mutations are constructed in the **path space**.



#### Metropolis Light Transport - Pseudo code

```
\bar{x} \leftarrow \text{INITIALPATH}()
image \leftarrow \{ array of zeros \}
for i \leftarrow 1 to N
        \bar{y} \leftarrow \text{MUTATE}(\bar{x})
        a \leftarrow \operatorname{ACCEPTPROB}(\bar{y}|\bar{x})
        if RANDOM() < a
            then \bar{x} \leftarrow \bar{y}
         RECORDSAMPLE(image, \bar{x})
return image
```

#### **Pros and Cons**

- **Pros** It is efficient for images that the **bidirectional method fails**.
  - We can **treat complicated functions** according to the mutation strategies.
- **Cons** Too **complex** to implement and **not flexible** enough.
  - Consider **proper mutation strategy** depended on environments.

#### Primary Sample Space MLT [C. Kelemen '02]

- Original MLT mutates samples in **path space**.
- Primary Sample Space MLT mutates samples in primary sample space.

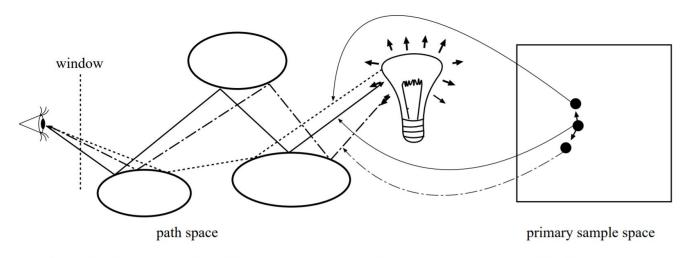
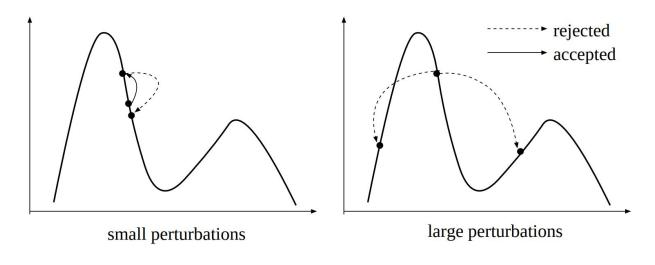


Figure 3: The correspondance between the mutations in the primary sample space and in the path space

#### Primary Sample Space MLT [C. Kelemen '02]

- In original MLT, the new sample **largely perturbed around a peak** of the function is easy to be **rejected**.
- because the **rejection probability** is proportional to the **ratio of the importances**.



#### Primary Sample Space MLT [C. Kelemen '02]

- So, we need to make the function relatively **flat**.
- By transformation to a simple space such as high-dimensional uniform distribution → primary sample space.
- We can just do **importance sampling** in the primary sample space.

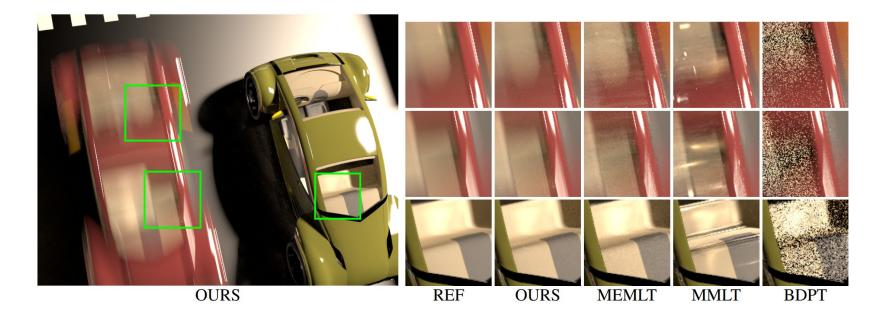
 $\mathbf{u}=T(\mathbf{z})$  : Transformation from path space to primary sample space

$$L^{*}(\mathbf{u}) = L(T^{-1}(\mathbf{u})) \cdot \left| \frac{dT^{-1}(\mathbf{u})}{d\mathbf{u}} \right| = \frac{L(T^{-1}(\mathbf{u}))}{t(\mathbf{u})} \quad \text{where} \quad \left| \frac{dT^{-1}(\mathbf{u})}{d\mathbf{u}} \right| = \frac{1}{t(\mathbf{u})}$$
  
Importance function 
$$I^{*}(\mathbf{u}) = \frac{I(T^{-1}(\mathbf{u}))}{t(\mathbf{u})}.$$

#### **Pros and Cons**

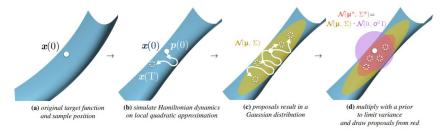
- **Pros** Achieve low variance by high acceptance ratio.
  - They make the importance function flat to reduce ratio of the importances.
- **Cons** Still difficult in complex function such as **highly glossy area**.
  - Even more difficult than the original MLT.

Anisotropic Gaussian Mutations for Metropolis Light Transport through Hessian-Hamiltonian Dynamics [T.-M. Li '15]



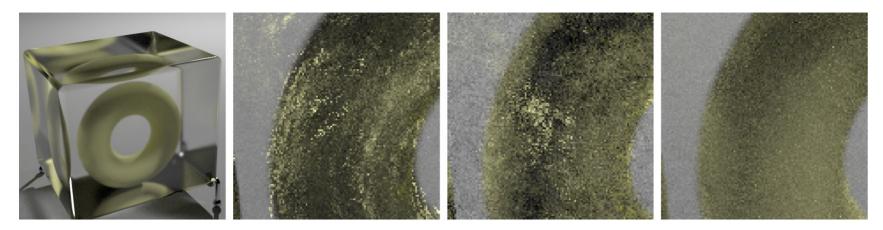
## Anisotropic Gaussian Mutations for Metropolis Light Transport through Hessian-Hamiltonian Dynamics [T.-M. Li '15]

- Inspired from **Hamiltonian Monte Carlo**, one kind of Markov Chain Monte Carlo methods.
- Captures the strong **anisotropy** of the light transport integrand using **Hessian** of measurement contribution function.



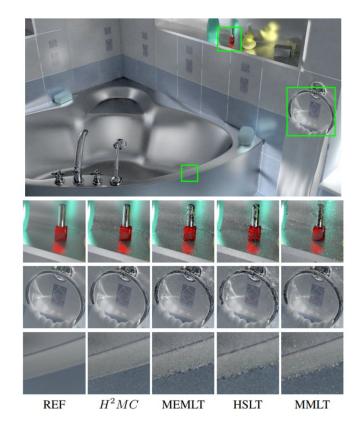
- Efficient for rendering **difficult light transport** such as highly-glossy transport (multi-bounce) combined with motion blur.

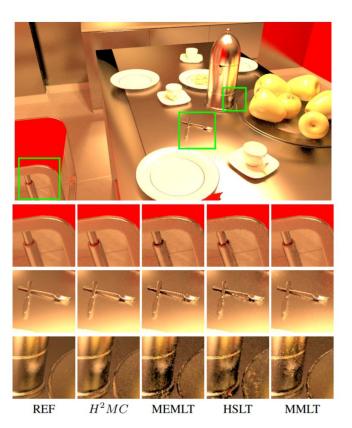
### Anisotropic Gaussian Mutations for Metropolis Light Transport through Hessian-Hamiltonian Dynamics [T.-M. Li '15]



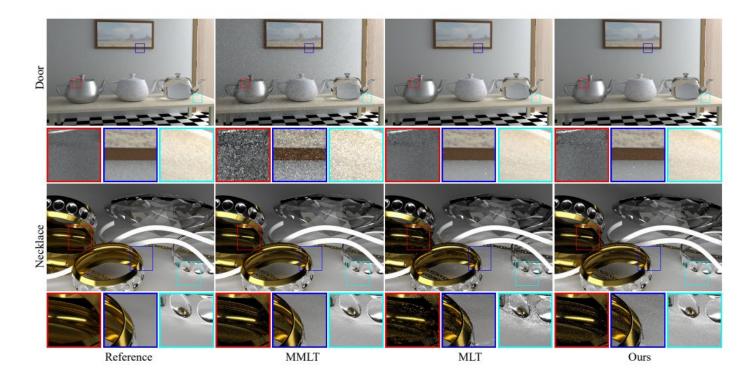
(a) TORUS (b) Kelemen et al., (c) Ours, (d) Ours, isotropic proposal isotropic proposal H<sup>2</sup>MC proposal

#### Equal time comparison



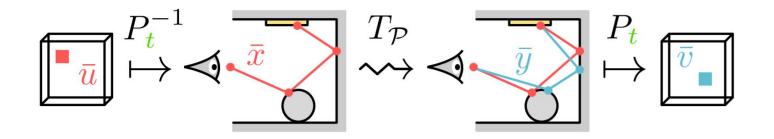


## Fusing State Spaces for Markov Chain Monte Carlo Rendering [H. Otsu '17]

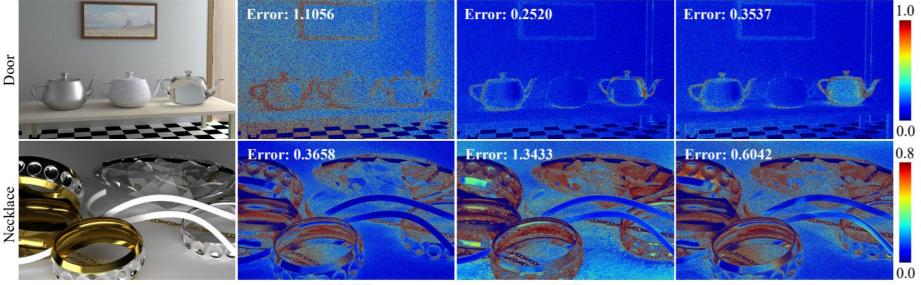


## Fusing State Spaces for Markov Chain Monte Carlo Rendering [H. Otsu '17]

- Fused mutations in the path space and the primary sample space.
- Possible to use **mutation strategies** designed for **one space** with another **mutation strategies** designed for respective **other space**.
- In the paper, they combined Manifold Exploration MLT (path space) and Multiplexed MLT (primary sample space)



#### Pixel-wise relative error



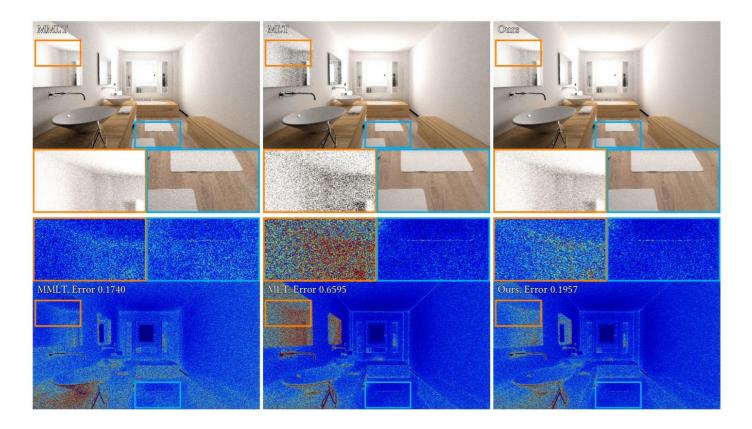
Reference

MMLT

MLT

Ours

#### Pixel-wise relative error



#### Conclusions

- 1. Anisotropic Gaussian Mutations for Metropolis Light Transport through Hessian-Hamiltonian Dynamics
  - a. Captures anisotropic rendering using Hessian
  - b. Good for difficult light transports

- 2. Fusing State Spaces for Markov Chain Monte Carlo Rendering
  - a. Possible to interconvert between the path space and the primary space.
  - b. Compromise of the spaces.

#### References

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- 2. H. Yang, *Lecture 5*, KAIST CS423 lecture notes, https://github.com/hongseok-yang/probprog19/tree/master/Lectures/Lecture5
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- 4. A. Benyoub, *Primary sample space and Multiplexed MLT*, 2014, http://anisb.github.io/slides.pdf
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   Oxford, UK: Blackwell Publishing, Inc, 2002.
- 6. T.-M. Li et al., *Anisotropic Gaussian Mutations for Metropolis Light Transport through Hessian-Hamiltonian Dynamics*, SIGGRAPH '15.
- 7. H. Otsu et al., *Fusing State Spaces for Markov Chain Monte Carlo Rendering*, ACM Trans. on Graphics, 2017.

# Thank you!