
CS482: Monte Carol Integration

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<http://sglab.kaist.ac.kr/~sungeui/ICG>

KAIST

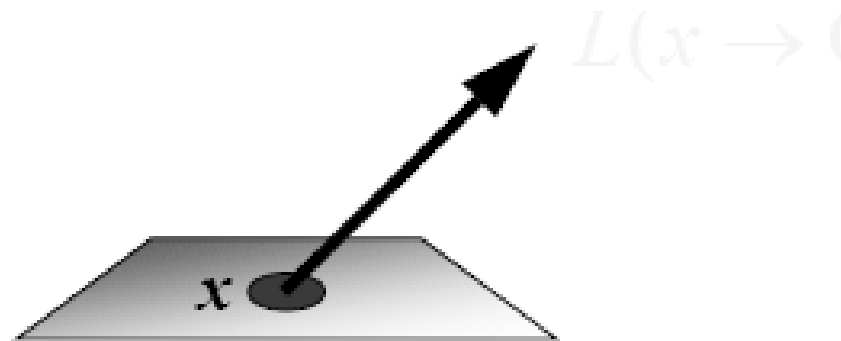


Class Objectives

- **Sampling approach for solving the rendering equation**
 - Monte Carlo integration
 - Estimator and its variance

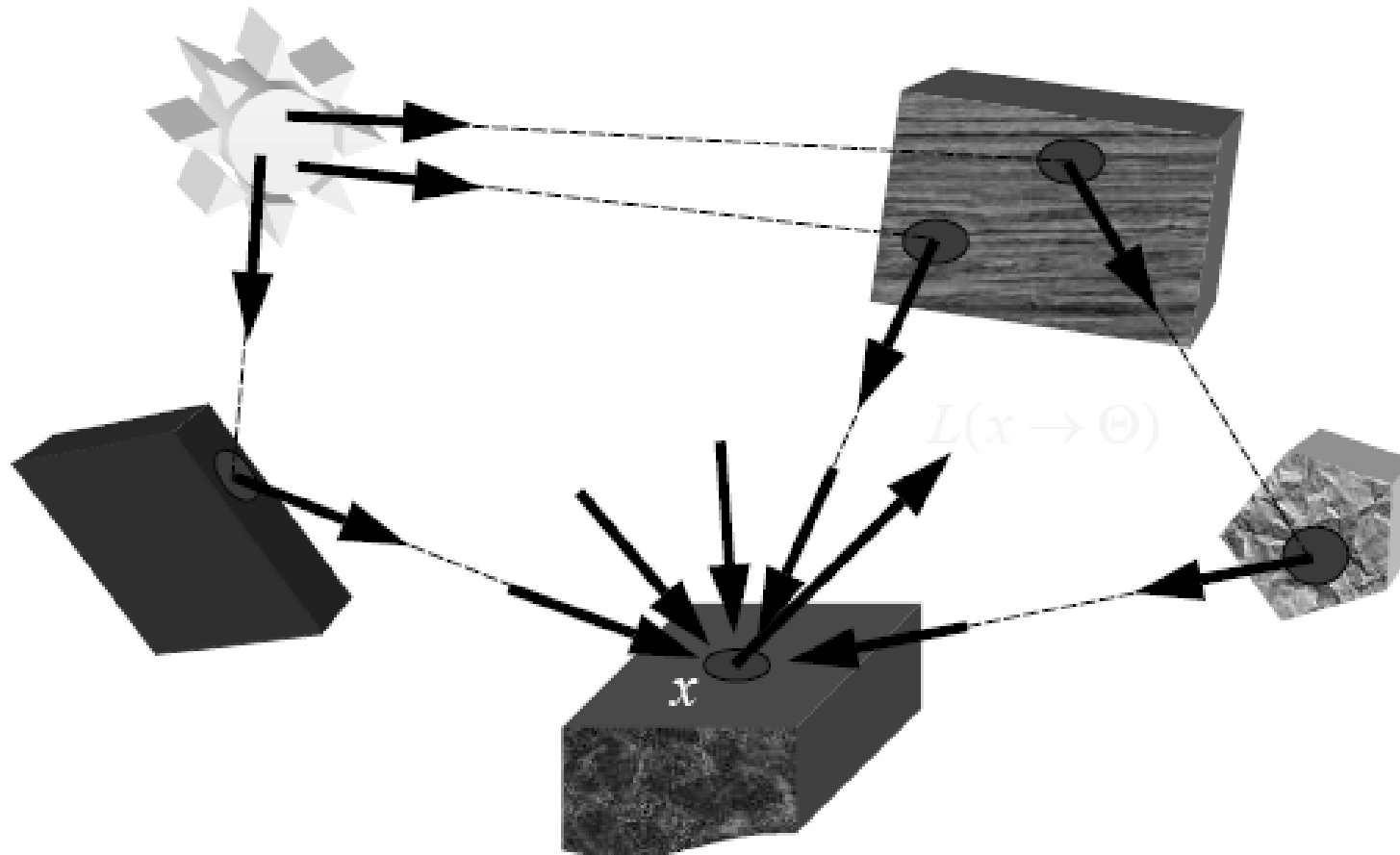
Radiance Evaluation

- **Fundamental problem in GI algorithm**
 - Evaluate radiance at a given surface point in a given direction
 - Invariance defines radiance everywhere else



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Radiance Evaluation

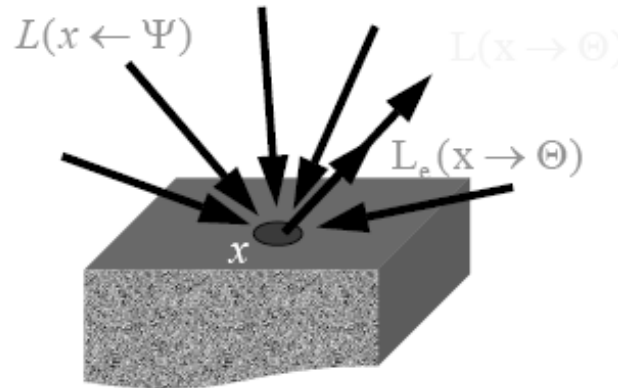


... find paths between sources and surfaces to be shaded

Why Monte Carlo?

- Radiance is hard to evaluate

$$\underline{L(x \rightarrow \Theta)} = \underline{L_e(x \rightarrow \Theta)} + \int_{\Omega_x} \underline{f_r(\Psi \leftrightarrow \Theta)} \cdot \underline{L(x \leftarrow \Psi)} \cdot \cos(\Psi, n_x) \cdot d\omega_\Psi$$



From kavita's slides

- Sample many paths
 - Integrate over all incoming directions
- Analytical integration is difficult
 - Need numerical techniques

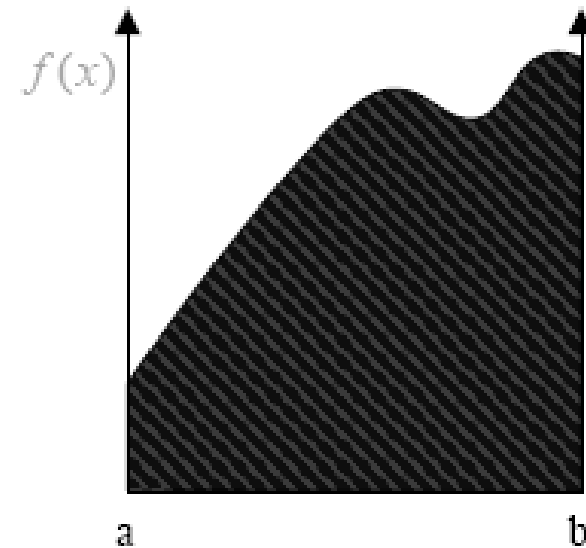
Monte Carlo Integration

- Numerical tool to evaluate integrals
 - Use sampling
- Stochastic errors
- Unbiased
 - On average, we get the right answer

Numerical Integration

- A one-dimensional integral:

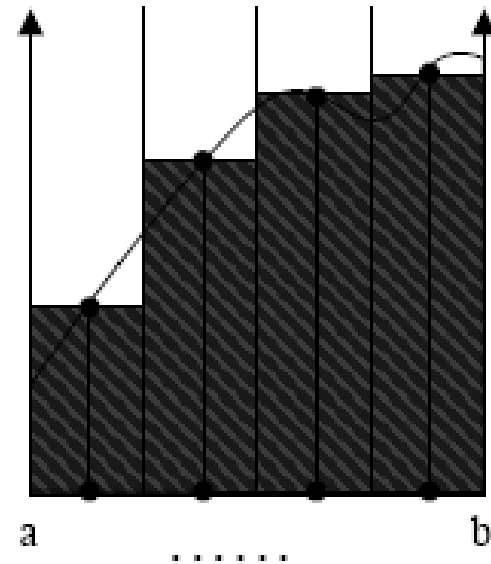
$$I = \int_a^b f(x) dx$$



Deterministic Integration

- Quadrature rules:

$$I = \int_a^b f(x) dx$$
$$\approx \sum_{i=1}^N w_i f(x_i)$$

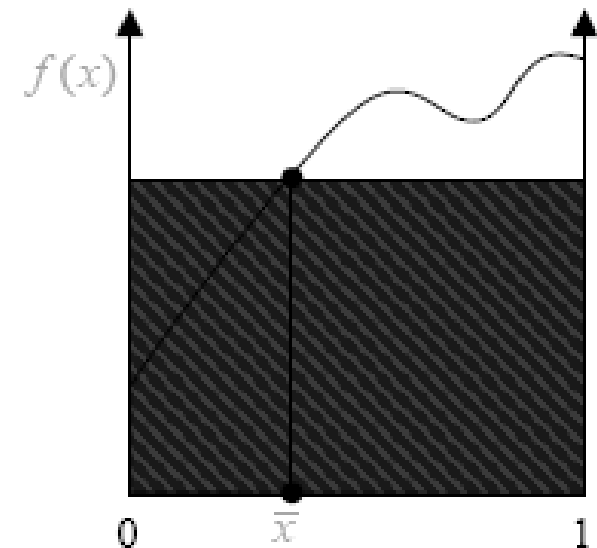


Monte Carlo Integration

Primary estimator:

$$I = \int_a^b f(x) dx$$

$$I_{prim} = f(\bar{x})$$

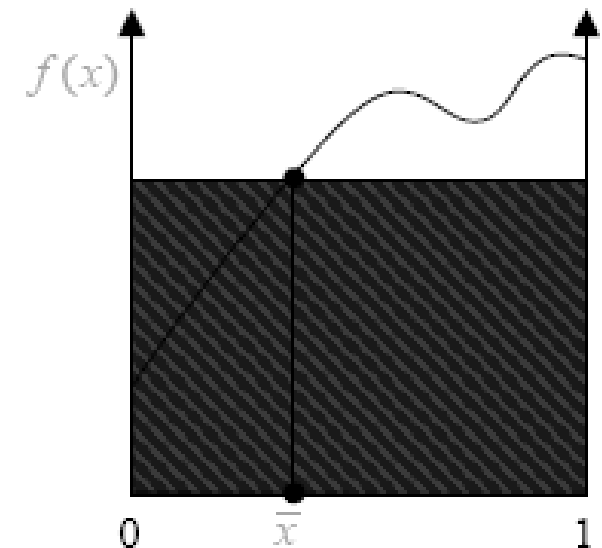


Monte Carlo Integration

Primary estimator:

$$I = \int_a^b f(x) dx$$

$$I_{prim} = f(\bar{x})$$



$$E(I_{prim}) = \int_0^1 f(x) p(x) dx = \int_0^1 f(x) 1 dx = I$$

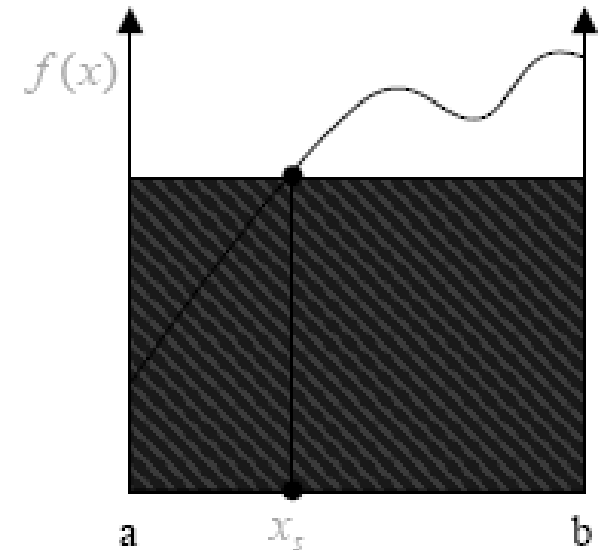
Unbiased estimator!

Monte Carlo Integration

Primary estimator:

$$I = \int_a^b f(x) dx$$

$$I_{prim} = f(x_s)(b - a)$$



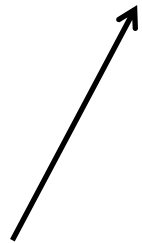
$$E(I_{prim}) = \int_a^b f(x)(b - a)p(x) dx = \int_a^b f(x)(b - a) \frac{1}{(b - a)} dx = I$$

Unbiased estimator!

Monte Carlo Integration: Error

Variance of the estimator → a measure of the stochastic error

$$\sigma_{prim}^2 = \int_a^b \left[\frac{f(x)}{p(x)} - I \right]^2 p(x) dx$$



- Consider $p(x)$ for estimate
- We will study it as importance sampling later

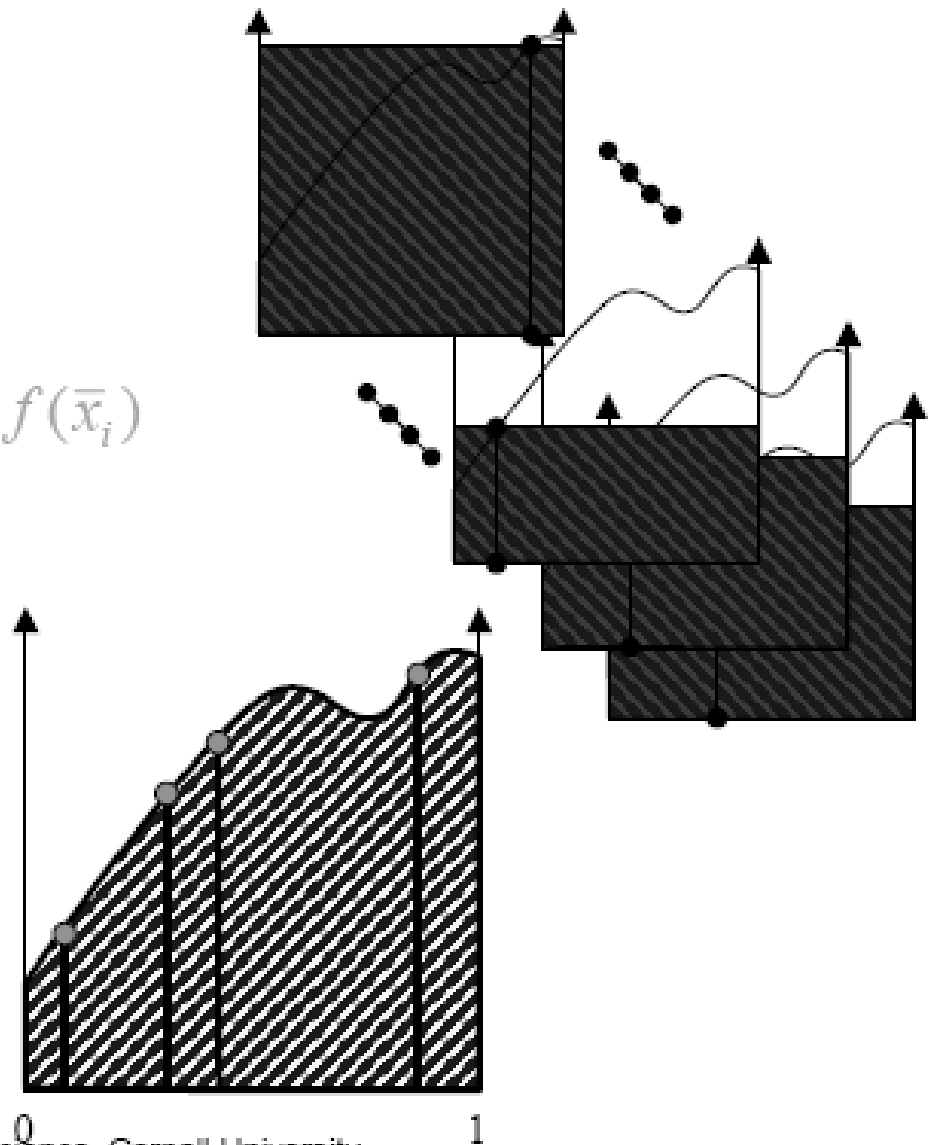
More samples

Secondary estimator

Generate N random samples x_i

Estimator:
$$\langle I \rangle = I_{\text{sec}} = \frac{1}{N} \sum_{i=1}^N f(\bar{x}_i)$$

Variance
$$\sigma_{\text{sec}}^2 = \sigma_{\text{prim}}^2 / N$$



Monte Carlo Integration

- Expected value of estimator

$$\begin{aligned} E[\langle I \rangle] &= E\left[\frac{1}{N} \sum_i^N \frac{f(x_i)}{p(x_i)}\right] = \frac{1}{N} \int \left(\sum_i^N \frac{f(x_i)}{p(x_i)}\right) p(x) dx \\ &= \frac{1}{N} \sum_i^N \int \left(\frac{f(x)}{p(x)}\right) p(x) dx \\ &= \frac{N}{N} \int f(x) dx = I \end{aligned}$$

– on ‘average’ get right result: **unbiased**

- Standard deviation σ is a measure of the stochastic error

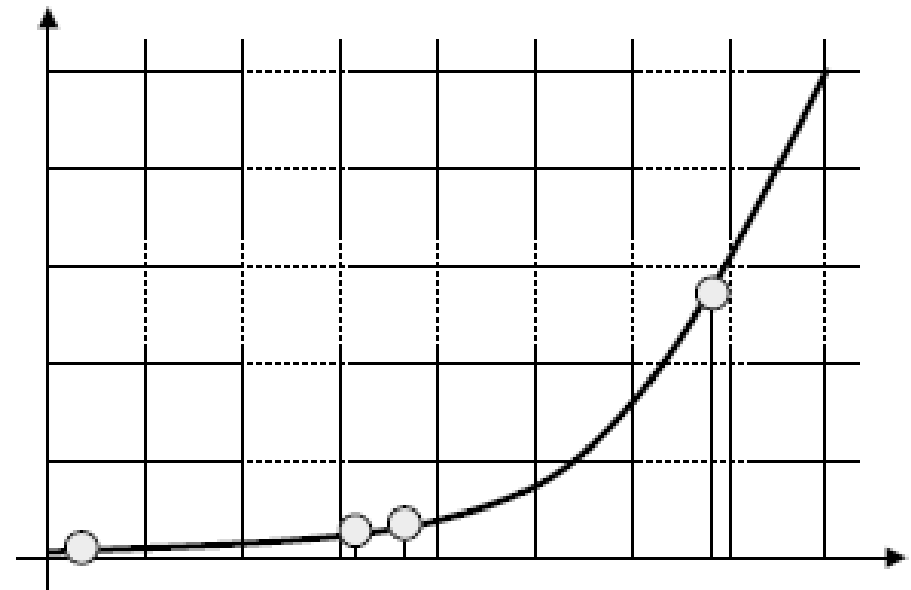
$$\sigma^2 = \frac{1}{N} \int_a^b \left[\frac{f(x)}{p(x)} - I\right]^2 p(x) dx$$

MC Integration - Example

– Integral $I = \int_0^1 5x^4 dx = 1$

– Uniform sampling

– Samples :



$$x_1 = .86 \quad \langle I \rangle = 2.74$$

$$x_2 = .41 \quad \langle I \rangle = 1.44$$

$$x_3 = .02 \quad \langle I \rangle = 0.96$$

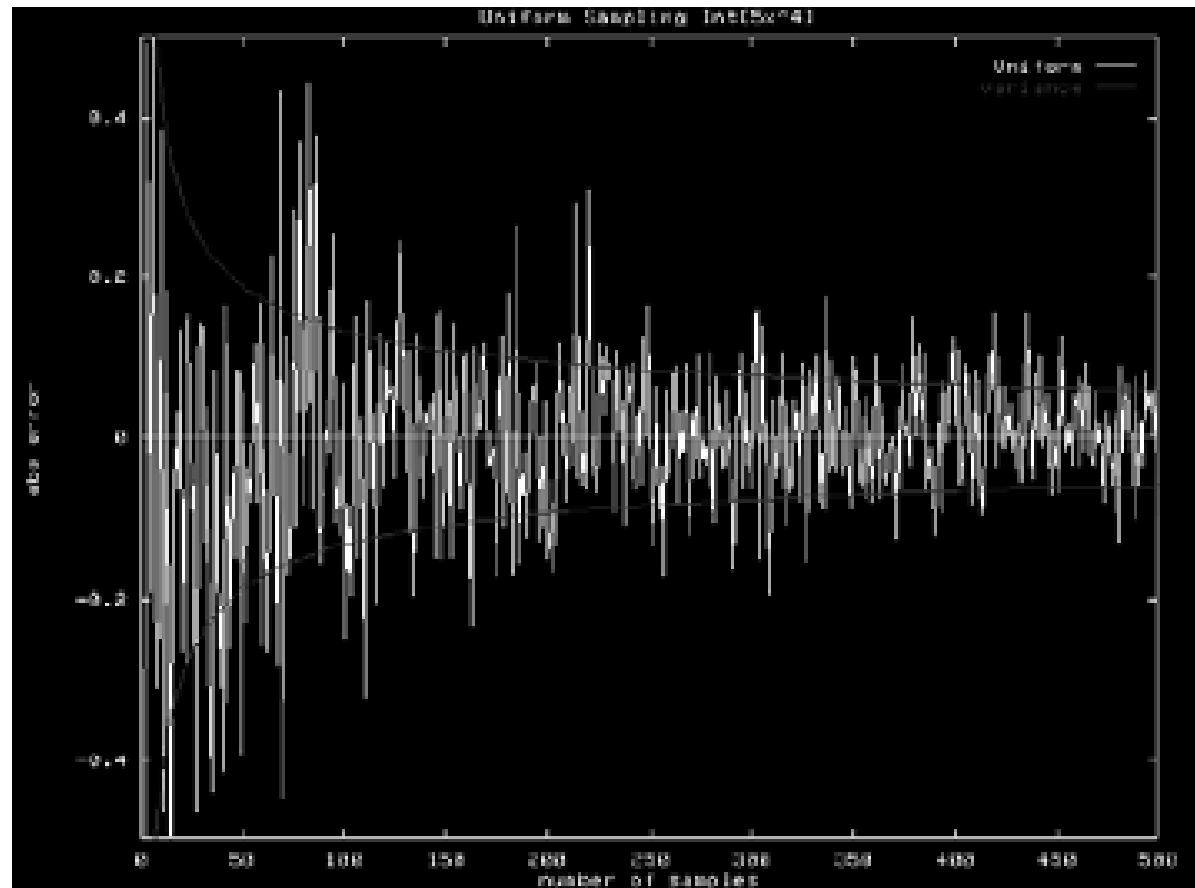
$$x_4 = .38 \quad \langle I \rangle = 0.75$$

MC Integration - Example

- Integral

$$I = \int_0^1 5x^4 dx = 1$$

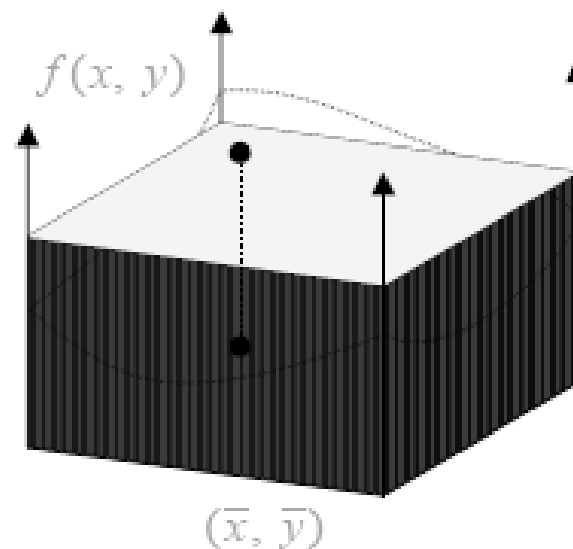
- Variance



MC Integration: 2D

- Primary estimator:

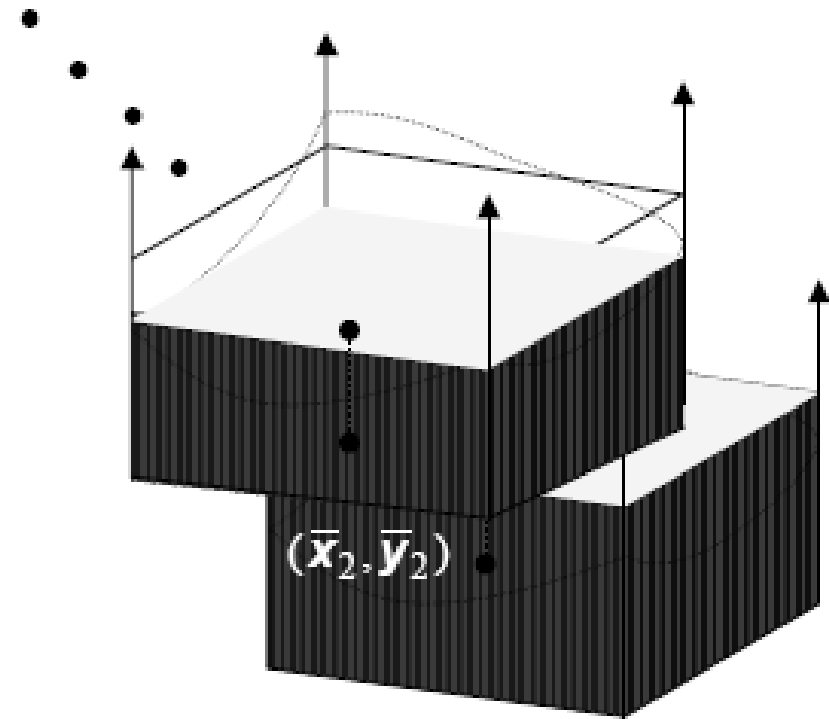
$$\bar{I}_{prim} = \frac{f(\bar{x}, \bar{y})}{p(\bar{x}, \bar{y})}$$



MC Integration: 2D

- Secondary estimator:

$$I_{\text{sec}} = \frac{1}{N} \sum_{i=1}^N \frac{f(\bar{x}_i, \bar{y}_i)}{p(\bar{x}_i, \bar{y}_i)}$$

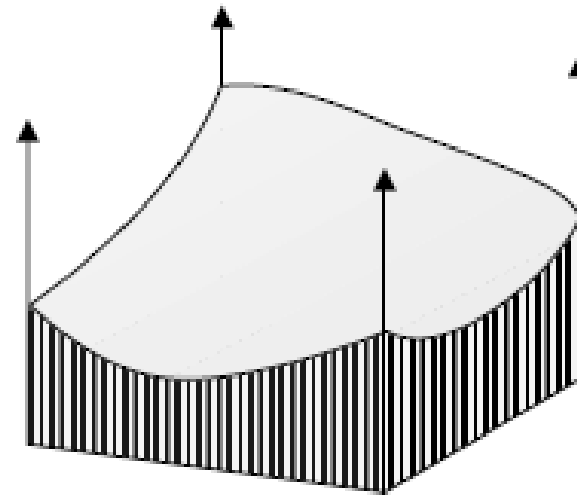


Monte Carlo Integration - 2D

- MC Integration works well for higher dimensions
- Unlike quadrature

$$I = \int_a^b \int_c^d f(x, y) dx dy$$

$$\langle I \rangle = \frac{1}{N} \sum_{i=1}^N \frac{f(x_i, y_i)}{p(x_i, y_i)}$$

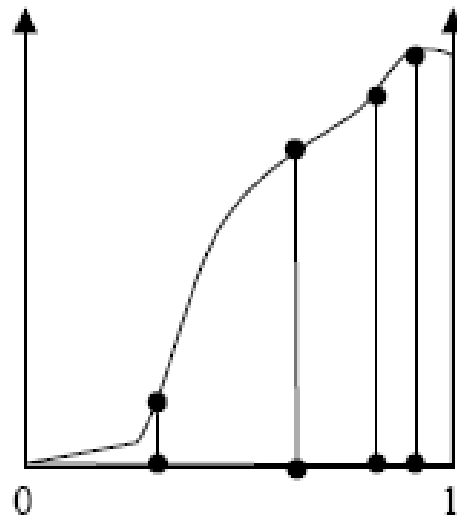


Advantages of MC

- Convergence rate of $O(\frac{1}{\sqrt{N}})$
- Simple
 - Sampling
 - Point evaluation
- General
 - Works for high dimensions
 - Deals with discontinuities, crazy functions, etc.

Importance Sampling

- Take more samples in important regions, where the function is large



From kavita's slides

Class Objectives were:

- **Sampling approach for solving the rendering equation**
 - Monte Carlo integration
 - Estimator and its variance

Next Time...

- Monte Carlo ray tracing

Homework

- **Go over the next lecture slides before the class**
- **Watch 2 SIG/I3D/HPG videos and submit your summaries every Tue. class**
 - **Just one paragraph for each summary**

Example:

Title: XXX XXXX XXXX

Abstract: this video is about accelerating the performance of ray tracing. To achieve its goal, they design a new technique for reordering rays, since by doing so, they can improve the ray coherence and thus improve the overall performance.

Any Questions?

- **Submit four times in Sep./Oct.**
- **Come up with one question on what we have discussed in the class and submit at the end of the class**
 - **1 for typical questions**
 - **2 for questions that have some thoughts or surprise me**