Image Search and Classification

Sung-Eui Yoon (윤성의)

Course URL: http://sglab.kaist.ac.kr/~sungeui



Acknowledgements

Collaborators

 My students, YuWing Tai, Pierre-Yves Laffont, Shih-Fu Chang, Junfeng He, Zhe Lin

• Funding sources

- Korea Research Foundation
- Ministry of Knowledge Economy
- Samsung
- Microsoft Research Asia
- Adobe



About the Instructor

Joined KAIST at 2007

Main research focus

 Handling of massive geometric data for various computer graphics and geometric problems

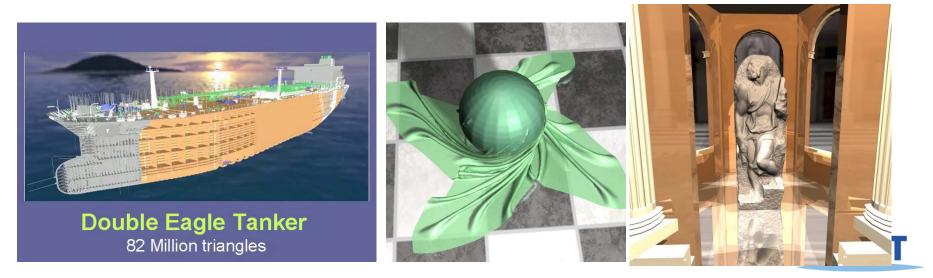
• Research for the topic

- Studied on nearest neighbor search about 10 years
- Moved to image search around 5 years ago



Main Research Focus

- Handle massive data for various computer graphics and geometric problems
- Paper and video
 - http://sglab.kaist.ac.kr/papers.htm
- YouTube videos
 - http://www.youtube.com/user/sglabkaist



Web-Scale Visual Data and Novel Applications

- Visual data are widely used for various communication and, and are more widely consumed at Web and mobile devices
 - YouTube, Facebook, Flickr, etc.
- Processing them requires scalable algorithms
- Web-scale visual data can enable new applications
 - Photo tourism,
 - Scene completion, etc.



About the Course

- We will focus on the following thing:
 - Broad understanding on image retrieval techniques and classification



Content-Based Image Retrieval (CBIR)

 Identify similar images given a userspecified image or other types of inputs

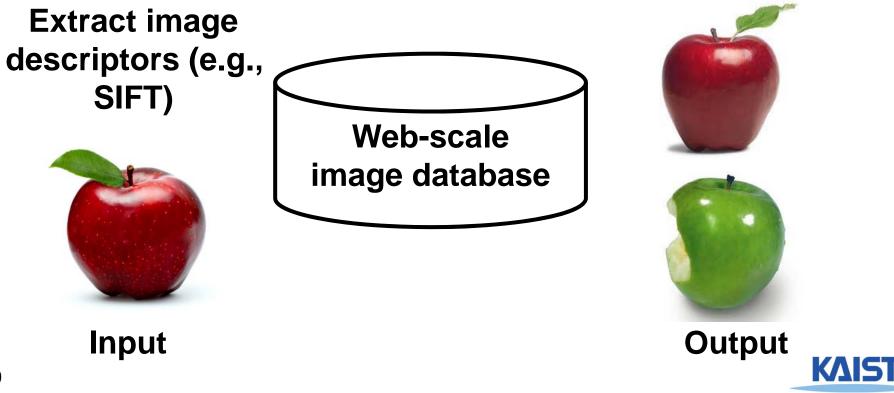






Content-Based Image Retrieval (CBIR)

 Identify similar images given a userspecified image or other types of inputs



Applications

- Search
- Image stitching
- Object/scene/location recognitions
- Robot motion planning
- Copyright detection



Panorama Stitching



(a) Matier data set (7 images)



(b) Matier final stitch

[Brown, Szeliski, and Winder, 2005]

http://www.cs.ubc.ca/~mbrown/autostitch/autostitch.html

Fei-Fei Li

iPhone version available

Lecture 12 - 32

9-Feb-11

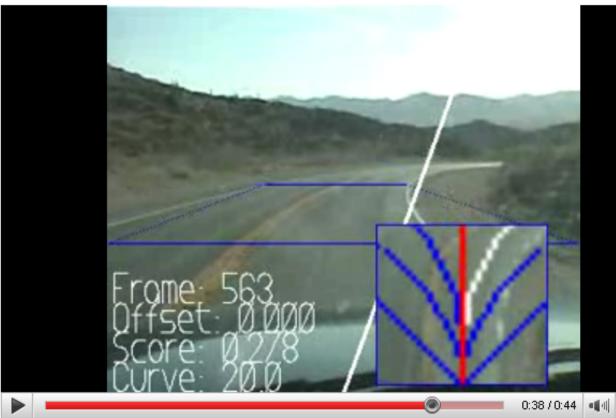
Object Detection





Robot Motion Planning

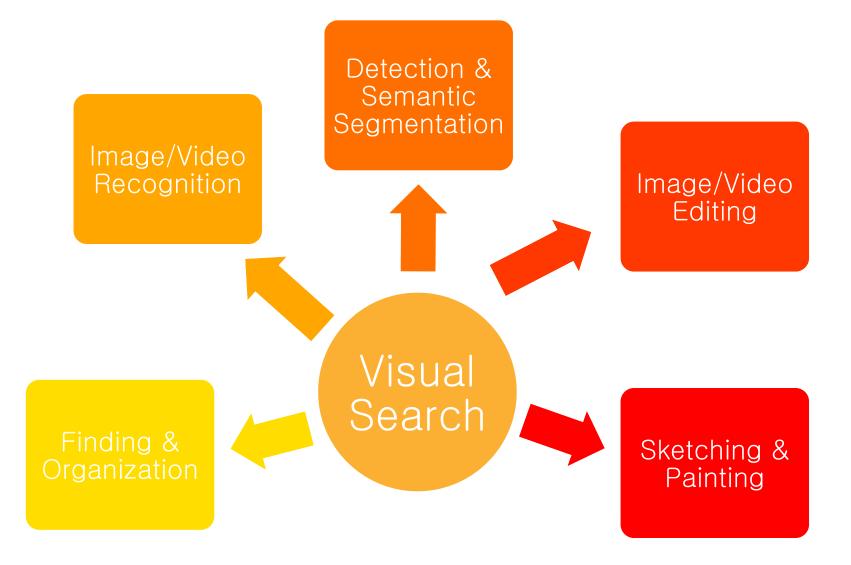
Autonomous robot vision 1



Autonomous robot http://www.youtube.com/watch?v=3SQiow-X3ko



Possible Application Domains





Issues for Web-Scale Multimedia Search

- Too many multimedia data and frequent updates
- Accuracy?
- Performance?
- Novel applications?



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Key Components

- Image representations
- Indexing algorithms
- Matching methods
- Classification, Localization, etc.
 - Apply image search (or nearest neighbor search)
 - Data-driven approach



Image Representations

• SIFT, GIST, etc.

Invariant to different transformations



Image Retrieval

 At pre-processing, build an database for efficient retrieval at runtime

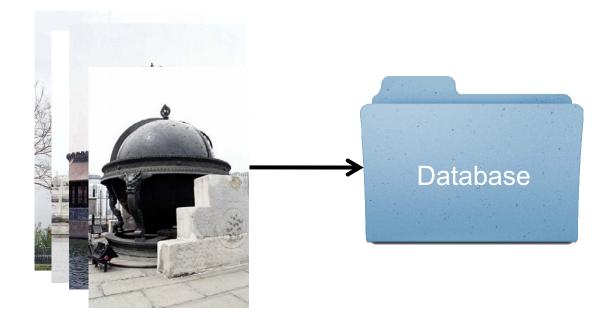




Image Retrieval

 At pre-processing, build an database for efficient retrieval at runtime

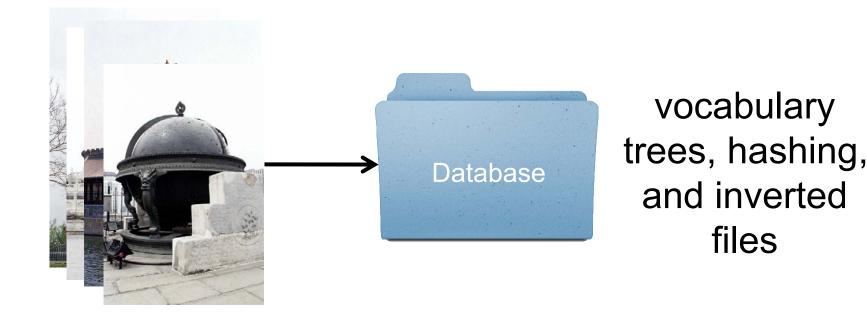




Image Retrieval: Runtime Procedure

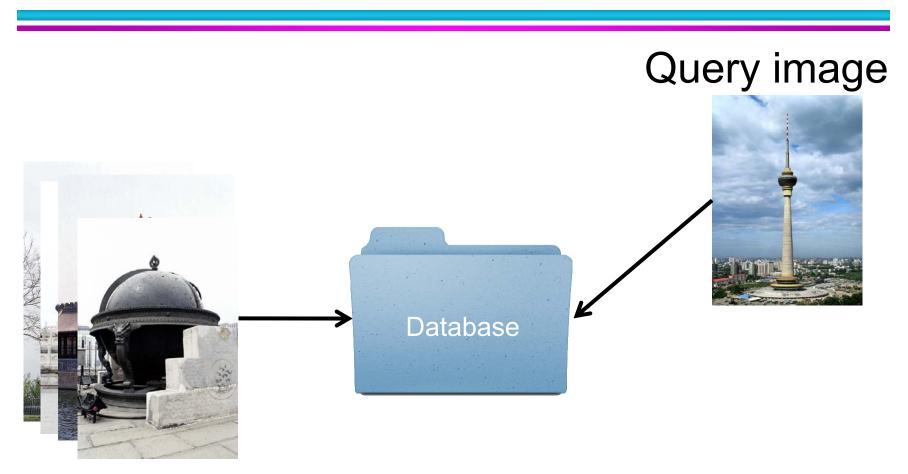




Image Retrieval: Runtime Procedure

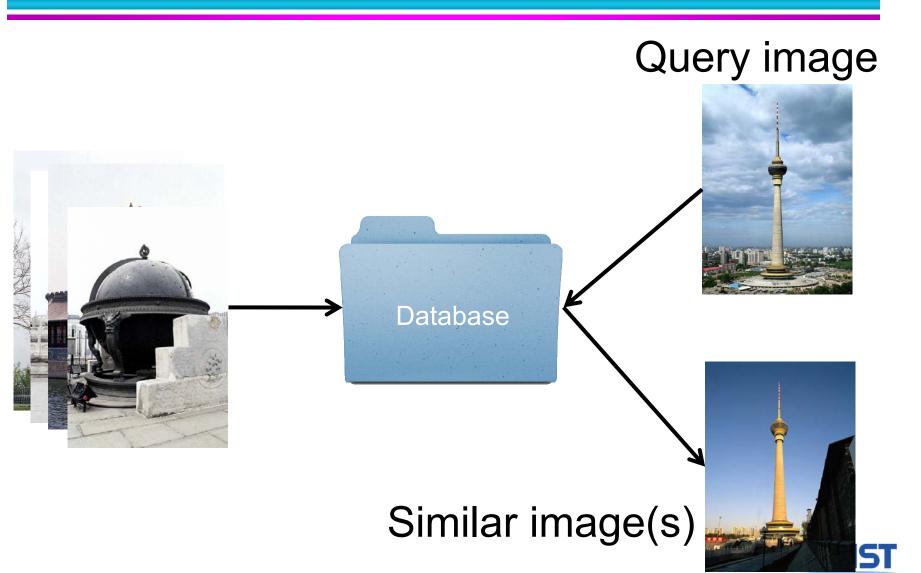
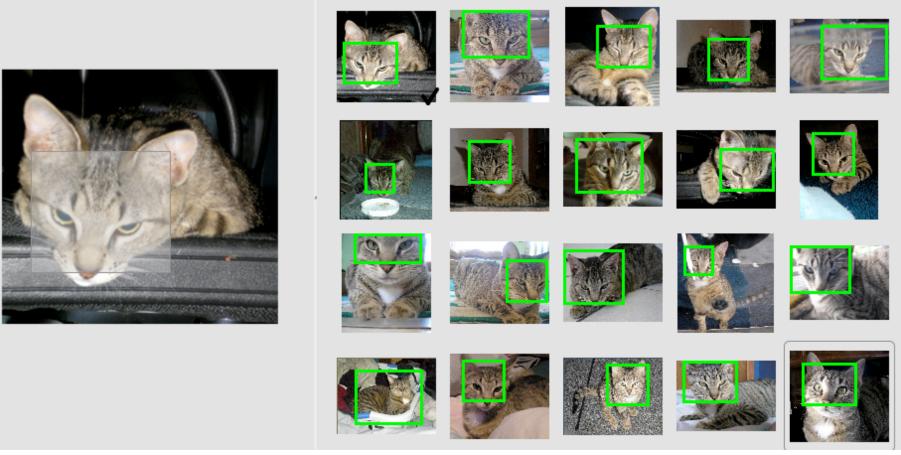


Image Retrieval with Spatially Constrained Similarity Measure

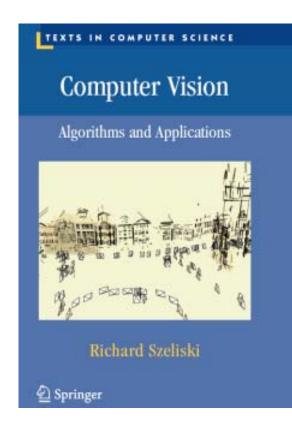


[Xiaohui Shen, Zhe Lin, Jon Brandt, Shai Avidan and Ying Wu, CVPR 2012]

Resource

- Reference
 - Computer vision: algorithms and applications

Its file is available (<u>http://szeliski.org/Book/</u>)





Other Resources

- Technical papers
 - CVPR, ICCV, ECCV, ACM MM, SIGGRAPH, etc.
 - Computer vision resource (<u>http://www.cvpapers.com/</u>)
- Course homepages
- Google or Google scholar





Bag-of-Words (BoW) Models

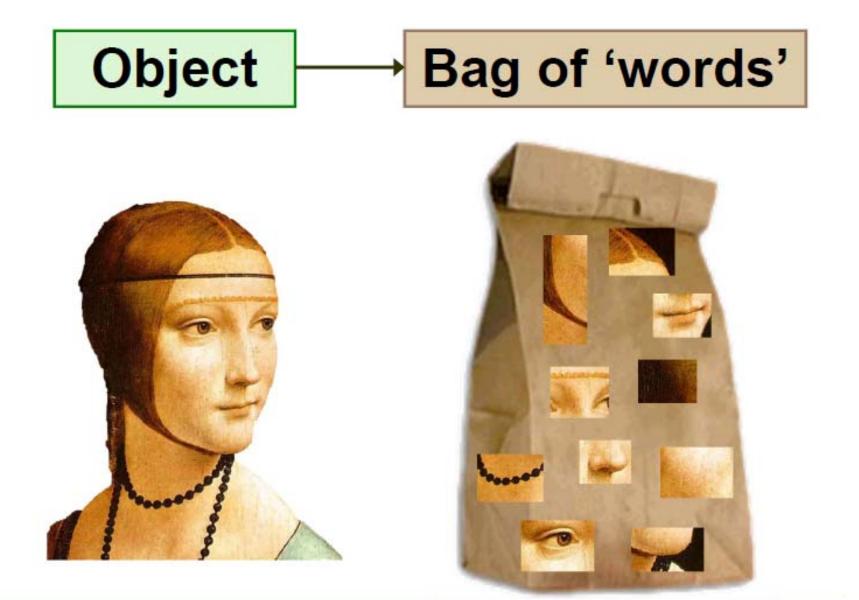
Sung-Eui Yoon (윤성의)

Course URL: <u>http://sglab.kaist.ac.kr/~sungeui</u>

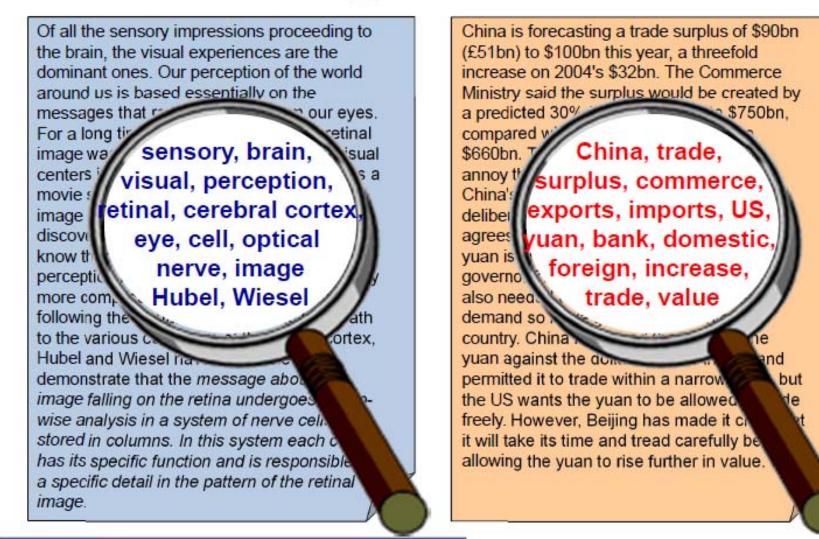


What we will learn today?

- Bag of Words models
 - Basic representation
 - Different learning and recognition algorithms



Analogy to documents



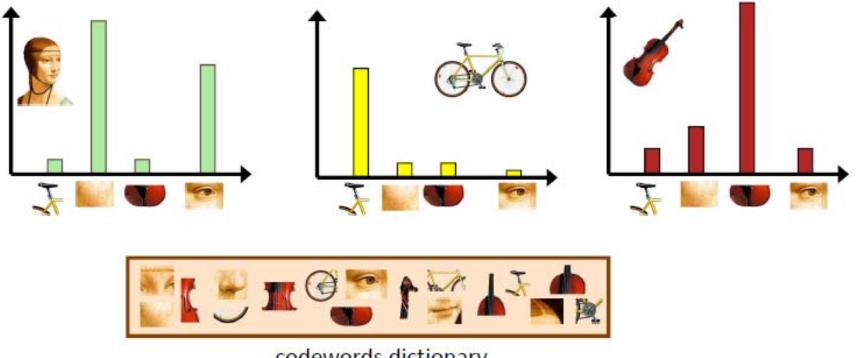
definition of "BoW"

Independent features

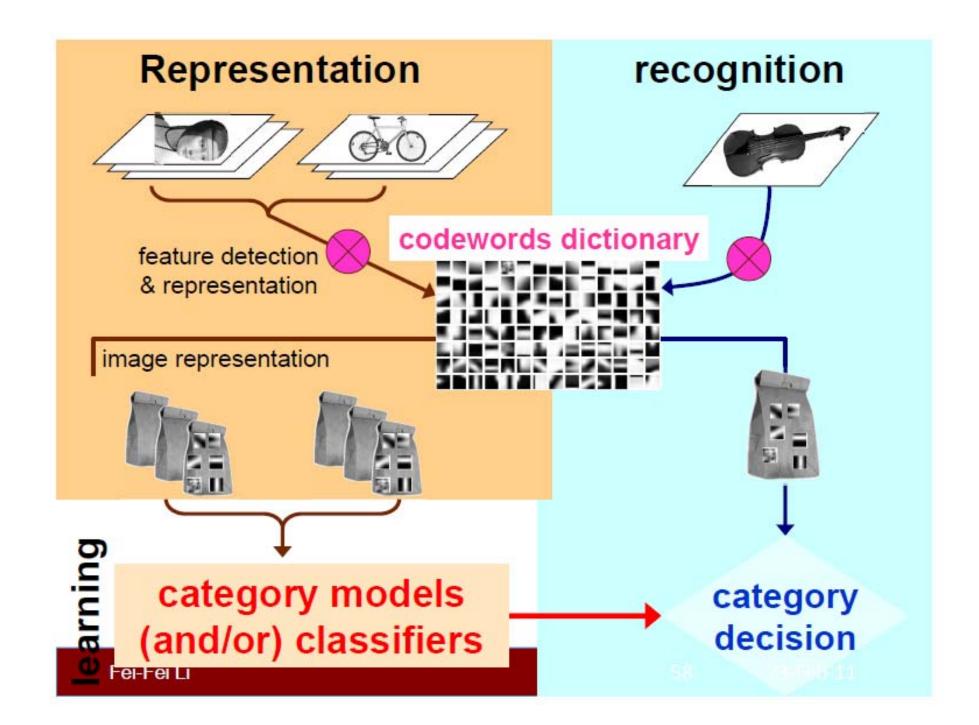


definition of "BoW"

- Independent features
- histogram representation

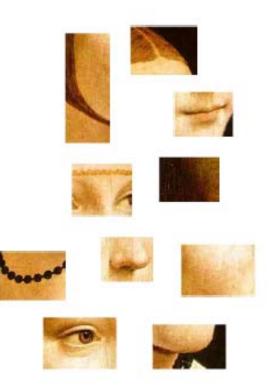


codewords dictionary



1.Feature detection and representation

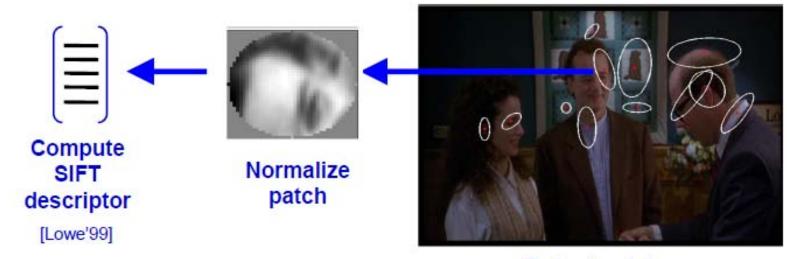




1.Feature detection and representation

- Regular grid
 - Vogel & Schiele, 2003
 - Fei-Fei & Perona, 2005
- Interest point detector
 - Csurka, Bray, Dance & Fan, 2004
 - Fei-Fei & Perona, 2005
 - Sivic, Russell, Efros, Freeman & Zisserman, 2005
- Other methods
 - Random sampling (Vidal-Naquet & Ullman, 2002)
 - Segmentation based patches (Barnard, Duygulu, Forsyth, de Freitas, Blei, Jordan, 2003)

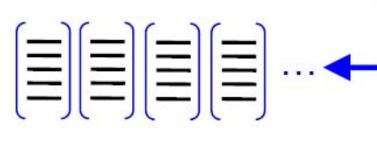
1.Feature detection and representation



Detect patches [Mikojaczyk and Schmid '02] [Mata, Chum, Urban & Pajdla, '02] [Sivic & Zisserman, '03]

Slide credit: Josef Sivic

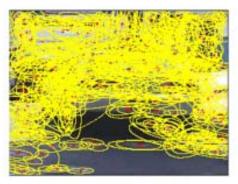
1.Feature detection and representation





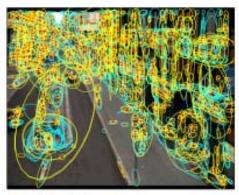
Representation

- Building blocks: Sampling strategies



Interest operators



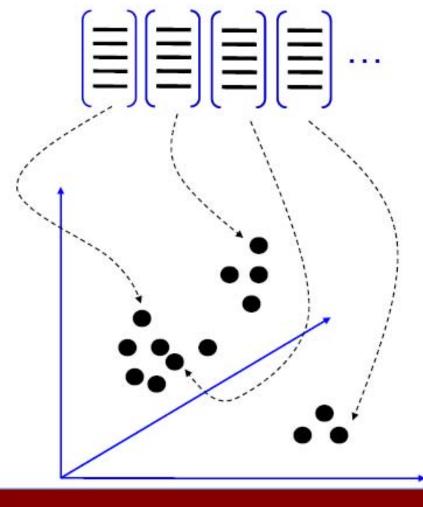


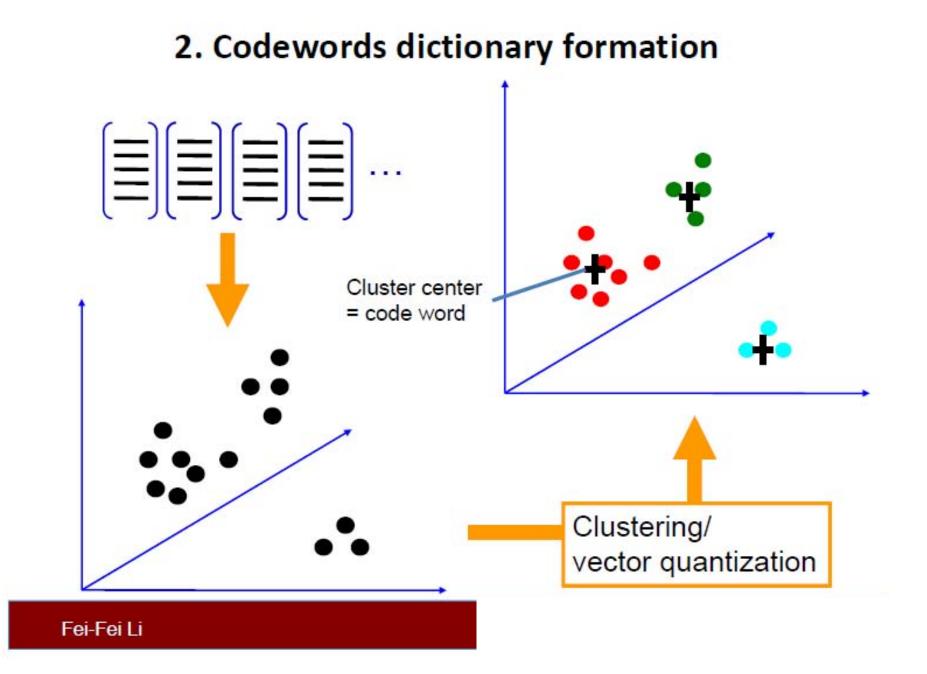
Multiple interest operators



Randomly

2. Codewords dictionary formation



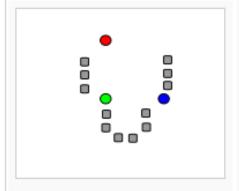


K-Means Clustering

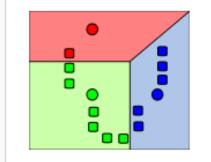
 Minimizing the within-cluster sum of squares (WCSS)

$$\underset{\mathbf{S}}{\operatorname{argmin}} \sum_{i=1}^{\kappa} \sum_{\mathbf{x}_j \in S_i} \|\mathbf{x}_j - \boldsymbol{\mu}_i\|^2$$

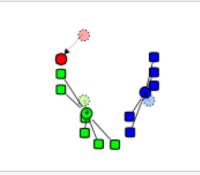
Demonstration of the standard algorithm



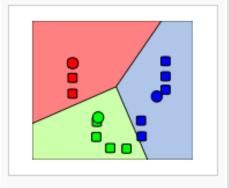
1) k initial "means" (in this case k=3) are randomly selected from the data set (shown in color).



 k clusters are created by associating every observation with the nearest mean. The partitions here represent the Voronoi diagram generated by the means.



 The centroid of each of the k clusters becomes the new means.



 Steps 2 and 3 are repeated until convergence has been reached.

_ _ _ _ _

2. Codewords dictionary formation

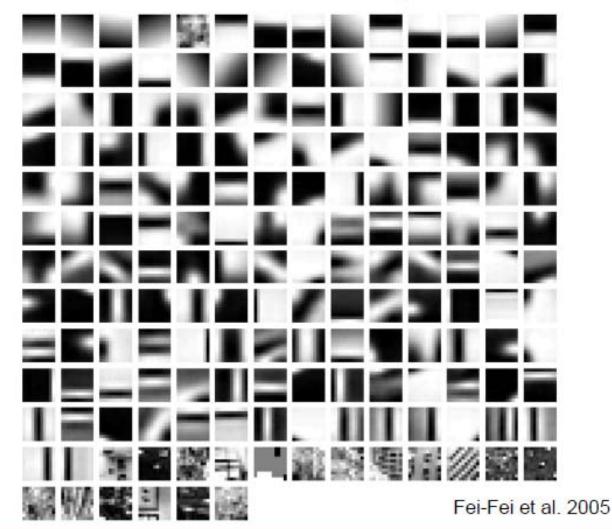
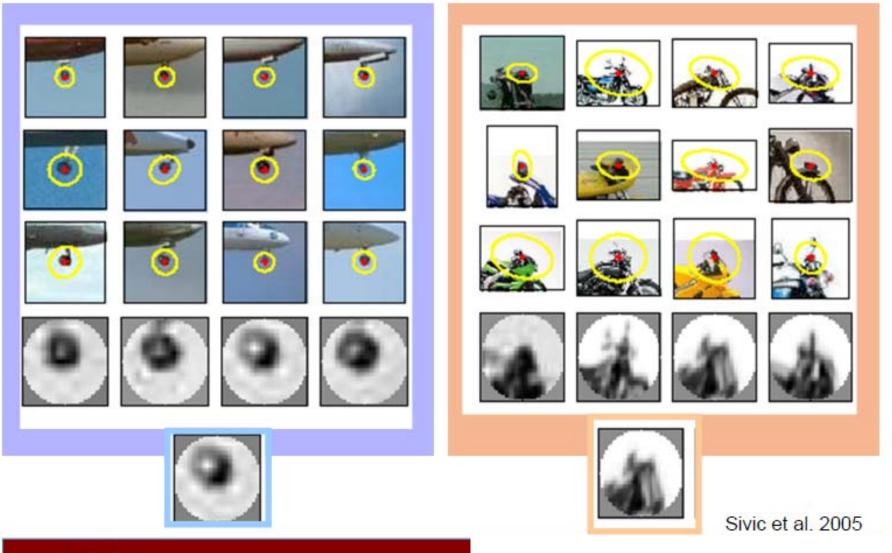
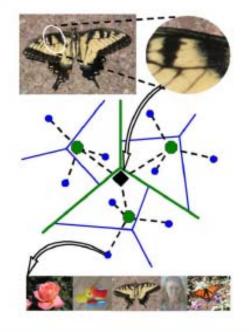


Image patch examples of codewords

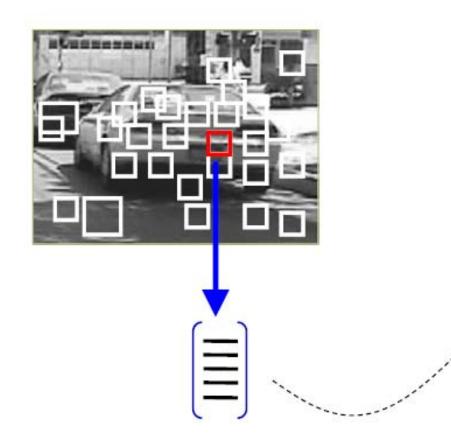


Visual vocabularies: Issues

- How to choose vocabulary size?
 - Too small: visual words not representative of all patches
 - Too large: quantization artifacts, overfitting
- Computational efficiency
 - Vocabulary trees
 (Nister & Stewenius, 2006)



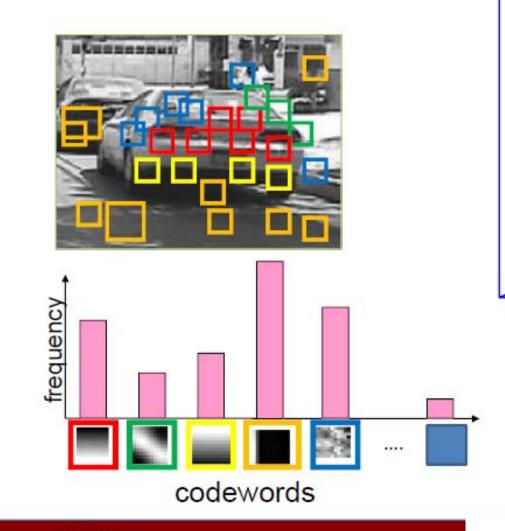
3. Bag of word representation

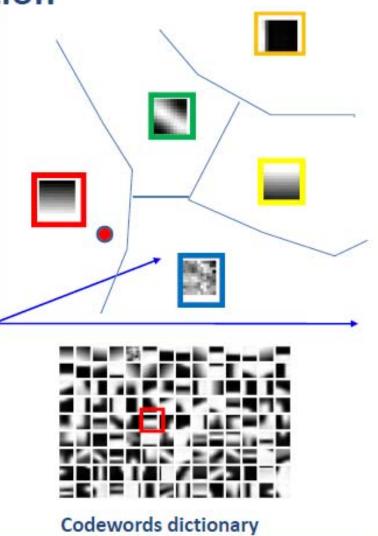


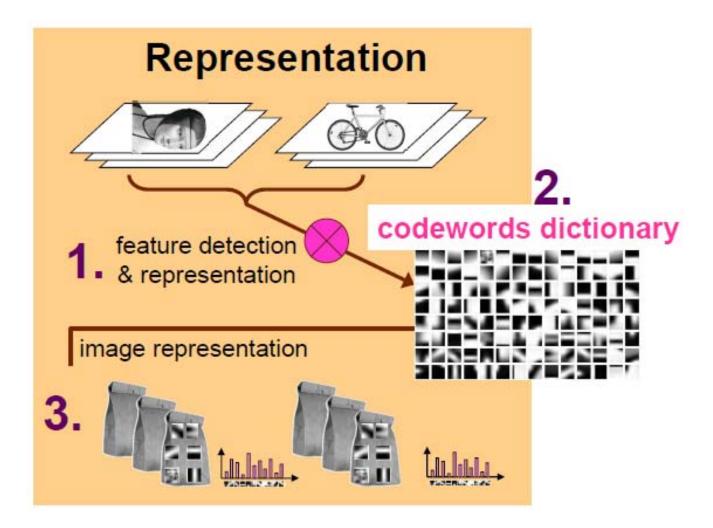
- Nearest neighbors assignment
- K-D tree search strategy

Codewords dictionary

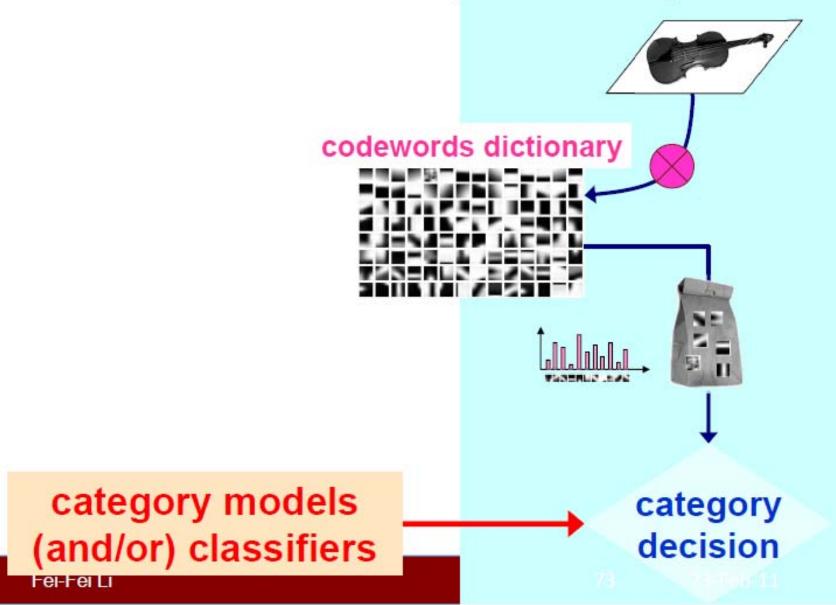
3. Bag of word representation





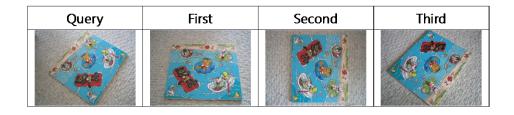


Learning and Recognition



PA2

- Understand and implement a basic image retrieval system
- Use the original UKBenchmark





11.447705.jpg



28.526271.jpg



29.273746.jpg









31.938790.jpg

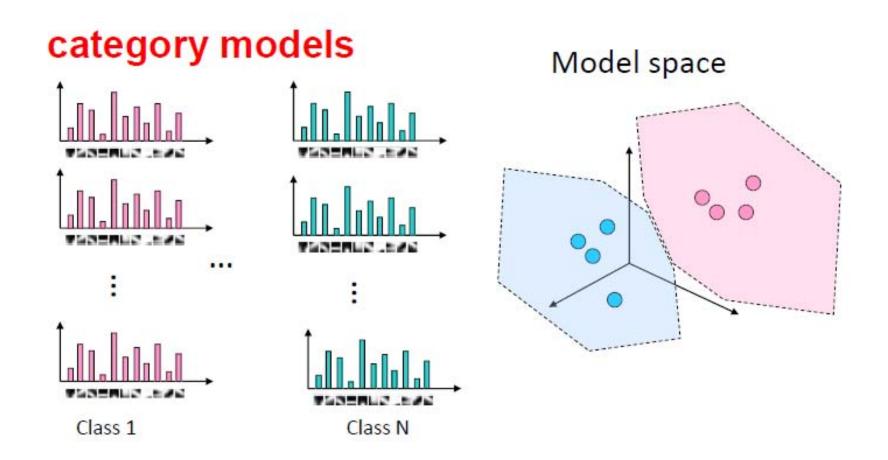


Learning and Recognition

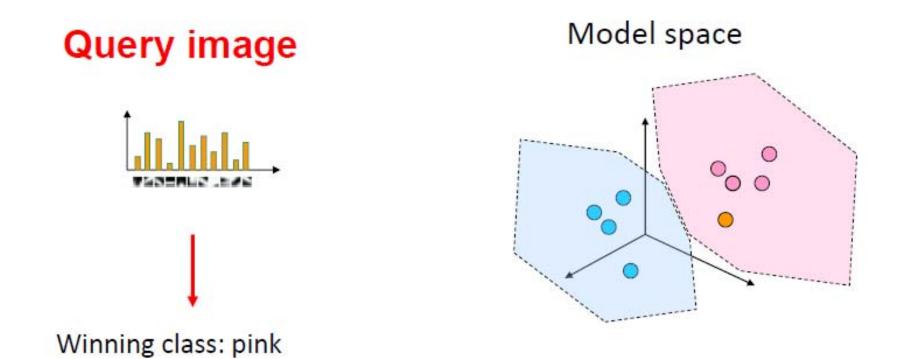
- Nearest neighbor
- SVM



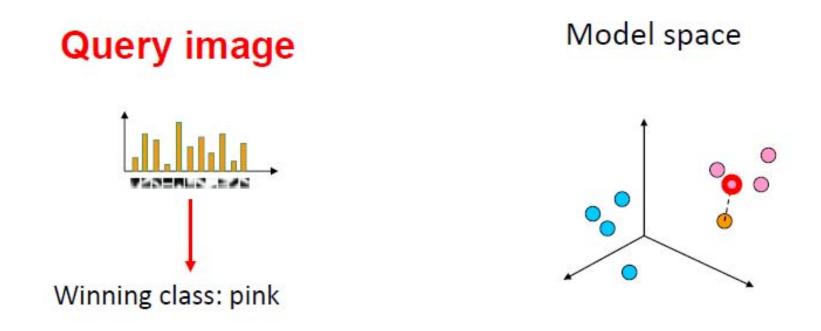
Discriminative classifiers



Discriminative classifiers



Nearest Neighbors classifier



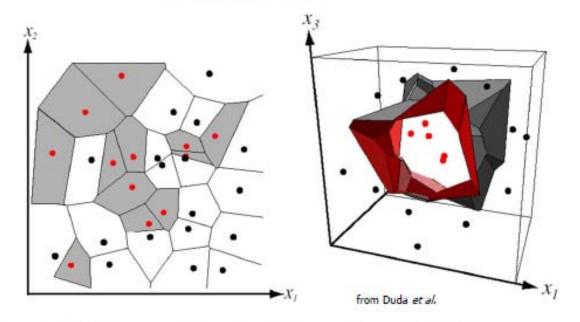
Assign label of nearest training data point to each test data point

K- Nearest Neighbors classifier



- For a new point, find the k closest points from training data
- Labels of the k points "vote" to classify
- Works well provided there is lots of data and the distance function is good

K- Nearest Neighbors classifier

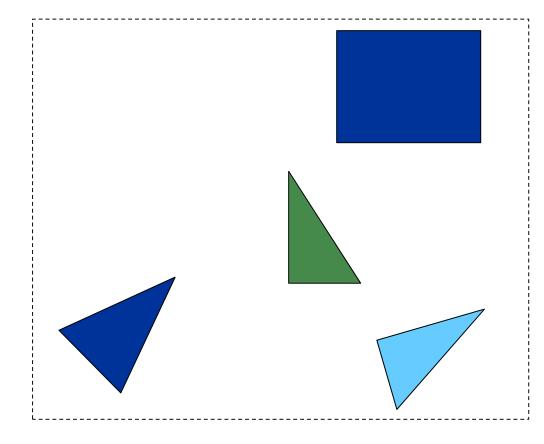


- Voronoi partitioning of feature space for 2-category 2-D and 3-D data
- For k dimensions: k-D tree = space-partitioning data structure for organizing points in a k-dimensional space
- Enable efficient search
- Nice tutorial: http://www.cs.umd.edu/class/spring2002/cmsc420-0401/pbasic.pdf

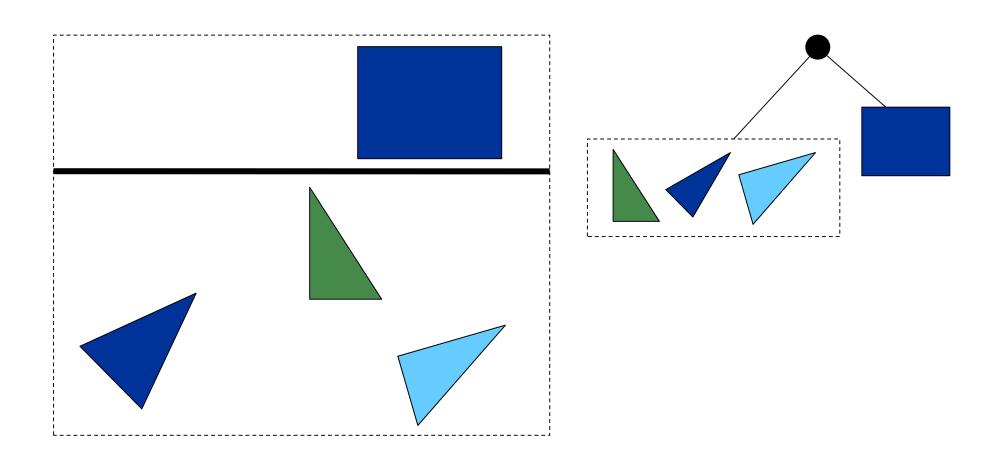
Overview of kd-Trees

- Binary spatial subdivision (special case of BSP tree)
- Split planes aligned on main axis
- Inner nodes: subdivision planes
- Leaf nodes: points

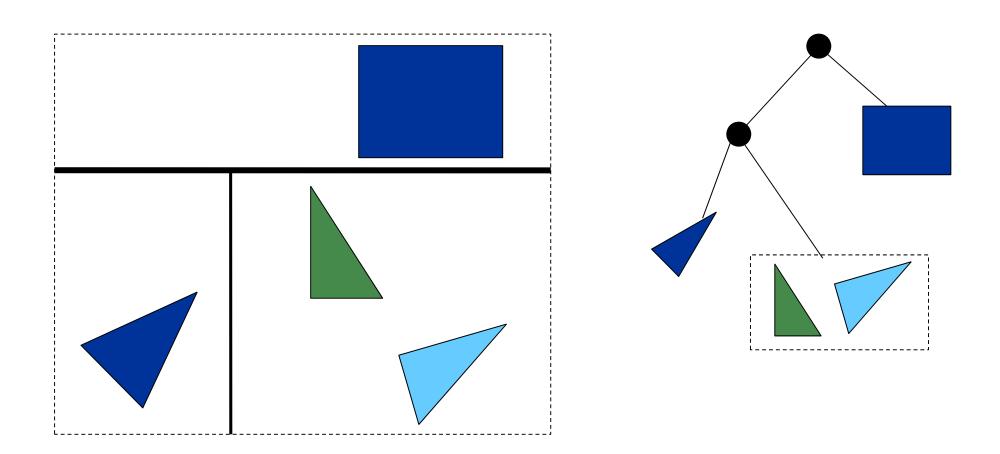




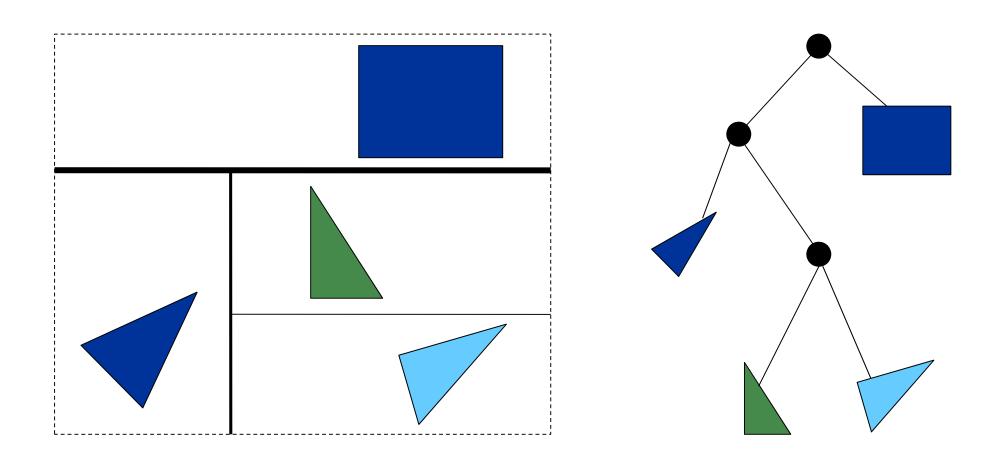














Nearest Neighbor Search with kd-tree

- Goal: find k nearest neighbors given a point
 - Commonly identify approximate, not exact nearest neighbors
- Apply a depth-first search
 - Traverse the tree with a stack
- Or, we can apply a best-bin first search
 - Traverse more promising nodes first
- Traverse until we visit a certain number of nodes



Hashing techniques

- Kd-trees are not scalable
- Hashing arise as better technology



Functions for comparing histograms

L1 distance

$$D(h_1, h_2) = \sum_{i=1}^{N} |h_1(i) - h_2(i)|$$

χ² distance

$$D(h_1, h_2) = \sum_{i=1}^{N} \frac{(h_1(i) - h_2(i))^2}{h_1(i) + h_2(i)}$$

Quadratic distance (cross-bin)

$$D(h_1, h_2) = \sum_{i,j} A_{ij} (h_1(i) - h_2(j))^2$$

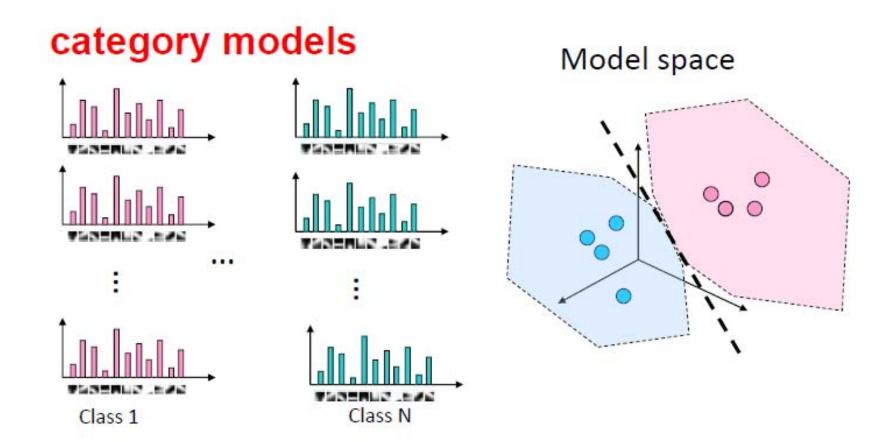
Jan Puzicha, Yossi Rubner, Carlo Tomasi, Joachim M. Buhmann: Empirical Evaluation of Dissimilarity Measures for Color and Texture. ICCV 1999

Learning and Recognition

- Nearest neighbor
- SVM

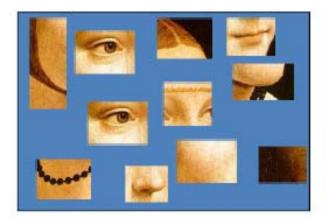


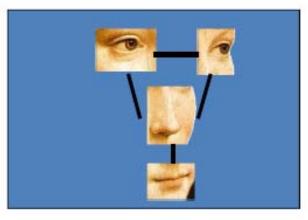
Discriminative classifiers (linear classifier)



Weakness of BoW the models

- No rigorous geometric information of the object components
- It's intuitive to most of us that objects are made of parts – no such information
- Not extensively tested yet for
 - View point invariance
 - Scale invariance
- Segmentation and localization unclear





What have we learned today?

- Bag of Words models
 - Basic representation
 - Different learning and recognition algorithms

Next Time...

Nearest neighbor search using hashing



Hashing Techniques

윤성의 (Sung-Eui Yoon)

Associate Professor KAIST

http://sglab.kaist.ac.kr



Image Retrieval

Finding visually similar images













Image Descriptor

High dimensional point

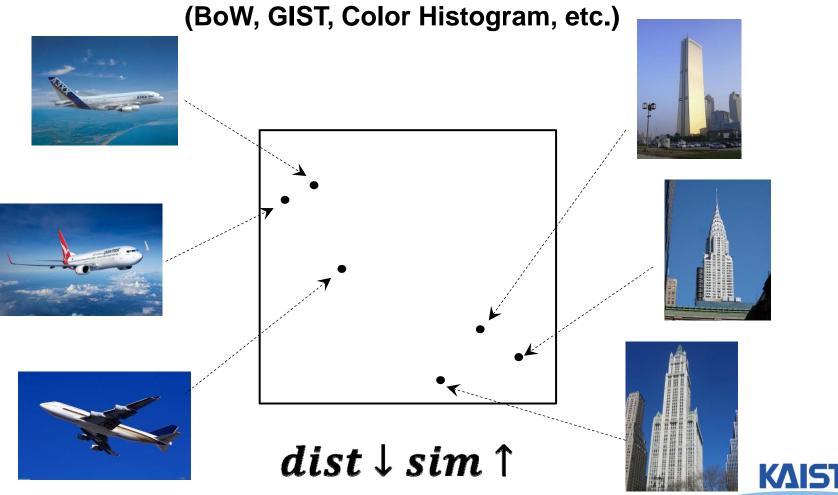
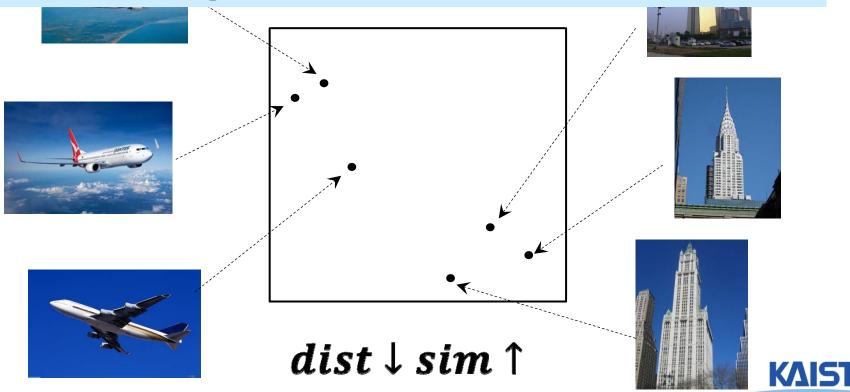


Image Descriptor

High dimensional point Nearest neighbor search (NNS) in high dimensional space



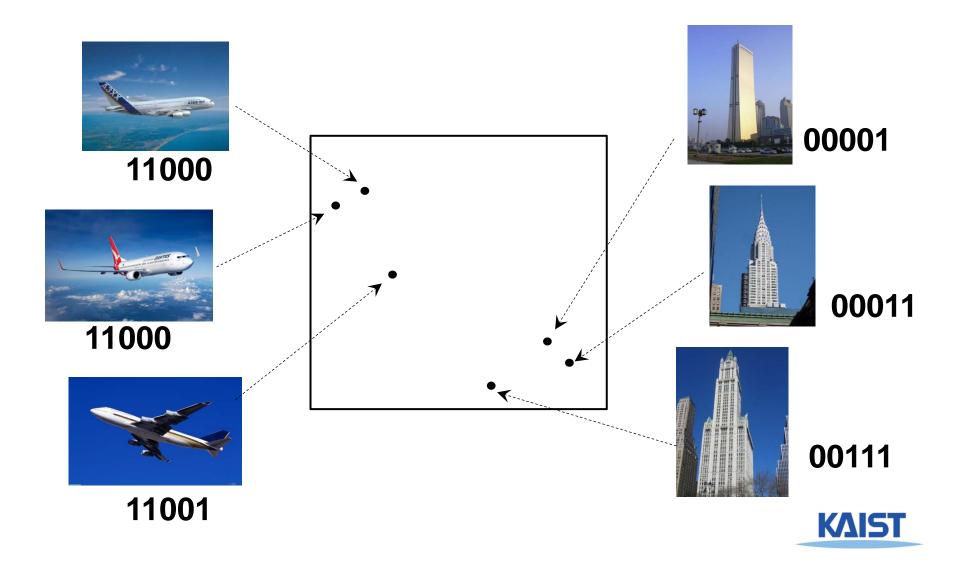
Challenge

	BoW	GIST
Dimensions	1000+	300+
1 image	4 KB+	1.2 KB+
1B images	3 TB+	1 TB+

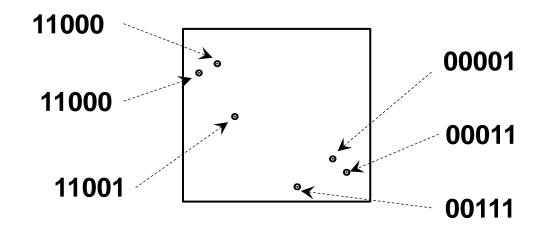
 $\frac{144 \text{ GB memory}}{1 \text{ billion images}} \approx \frac{128 \text{ bits}}{1 \text{ image}}$



Binary Code



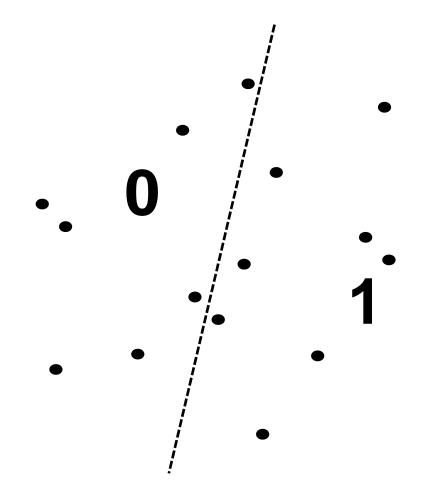
Binary Code



- * Benefits
 - Compression
 - Very fast distance computation (Hamming Distance, XOR)

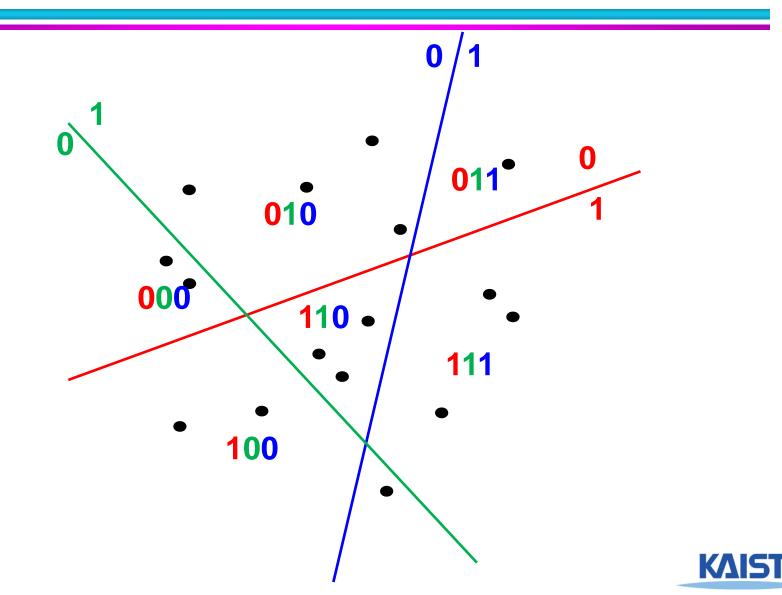


Hyper-Plane based Binary Coding

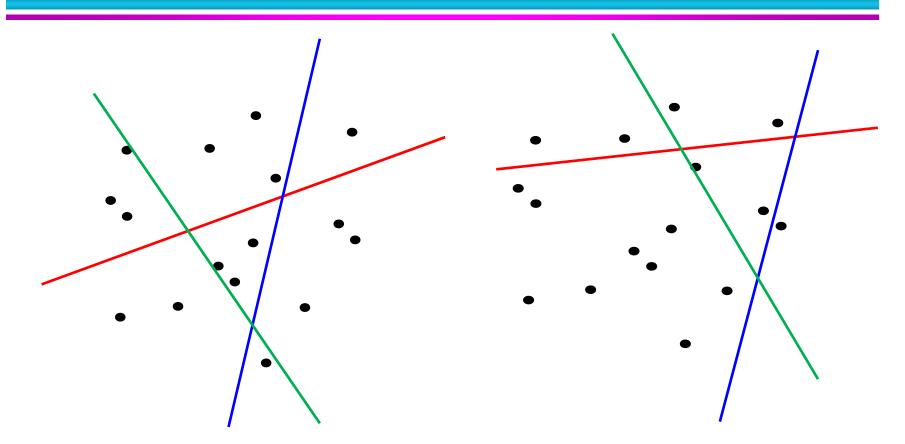




Hyper-Plane based Binary Coding



Good and Bad Hyper-Planes



Previous work focused on how to determine good hyper-planes

Previous Work

- Random hyper-planes from a specific distribution [Indyk STOC 1998, Raginsky NIPS 2009]
- Spectral graph partitioning [Yeiss, NIPS 2008]
- Minimize quantization error [Gong, CVPR 2011 oral session]
- Independent component analysis [He, CVPR 2011 oral session]
- Support Vector Machine [Joly, CVPR 2011]



Components of Spherical Hashing

- Spherical hashing
- Hyper-sphere setting strategy
- Spherical Hamming distance

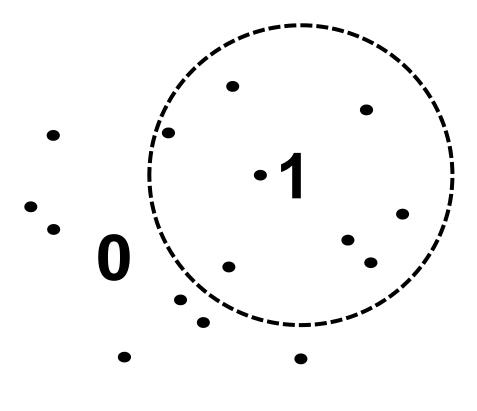


Components of Spherical Hashing

- Spherical hashing
- Hyper-sphere setting strategy
- Spherical Hamming distance

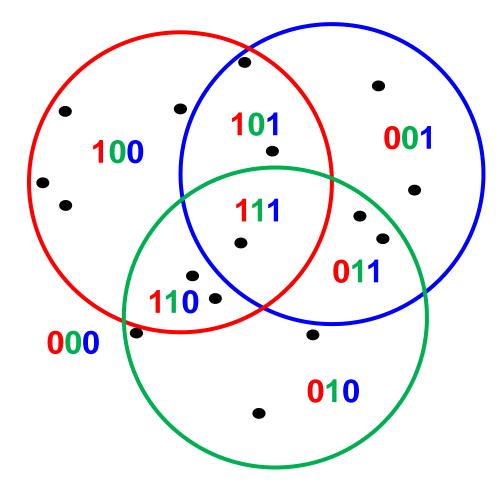


Spherical Hashing [Heo et al., CVPR 12]



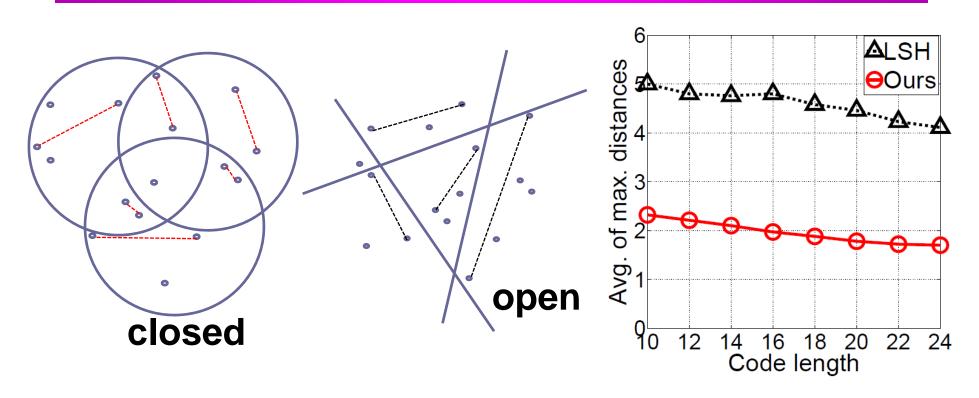


Spherical Hashing [Heo et al., CVPR 12]





Hyper-Sphere vs Hyper-Plane



Average of maximum distances within a partition: - Hyper-spheres gives tighter bound!



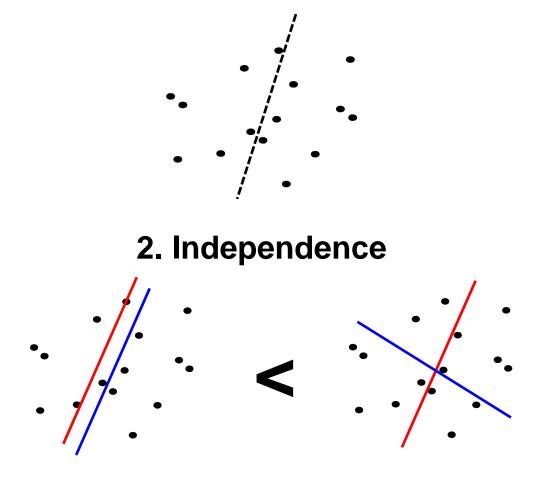
Components of Spherical Hashing

- Spherical hashing
- Hyper-sphere setting strategy
- Spherical Hamming distance



Good Binary Coding [Yeiss 2008, He 2011]

1. Balanced partitioning

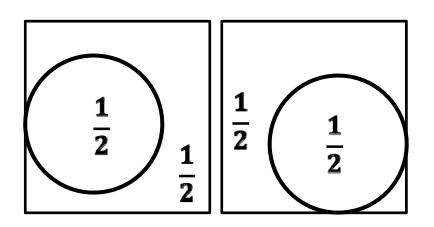


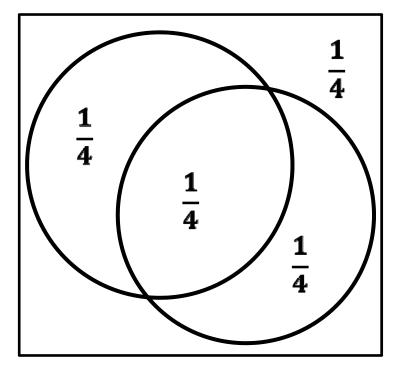


Intuition of Hyper-Sphere Setting

1. Balance

2. Independence

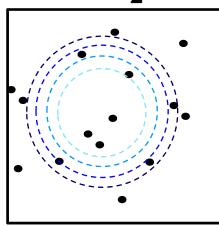






Hyper-Sphere Setting Process

- 1. Balance
- by controlling radius for $n(S) = \frac{N}{2}$



2. Independence - by moving two hyperspheres for $n(S_1 \cap S_2) = \frac{N}{4}$

Iteratively repeat step 1, 2 until convergence.

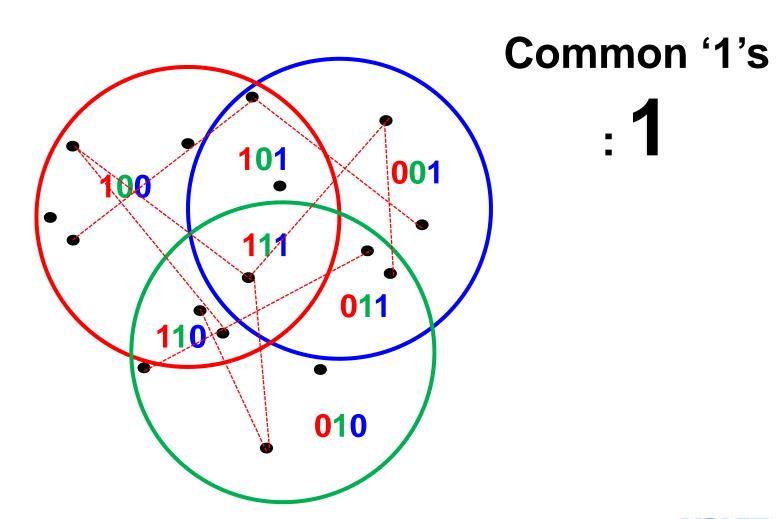


Components of Spherical Hashing

- Spherical hashing
- Hyper-sphere setting strategy
- Spherical Hamming distance

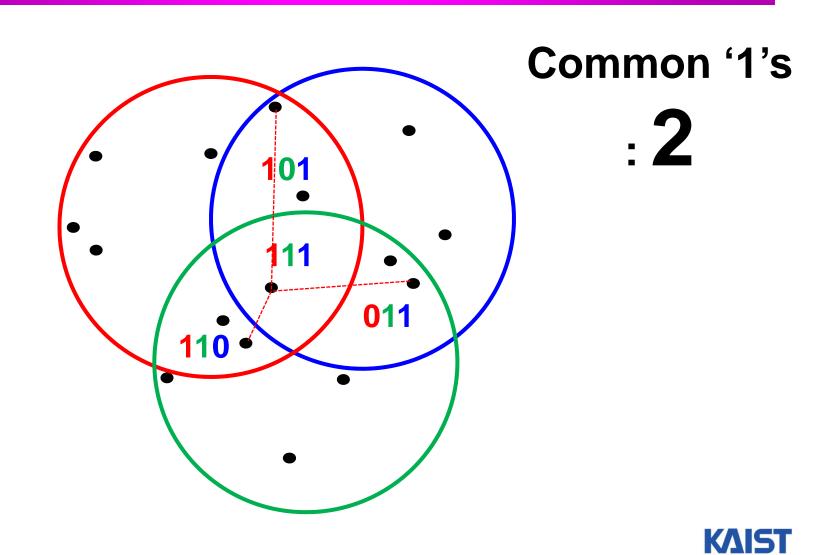


Max Distance and Common '1'



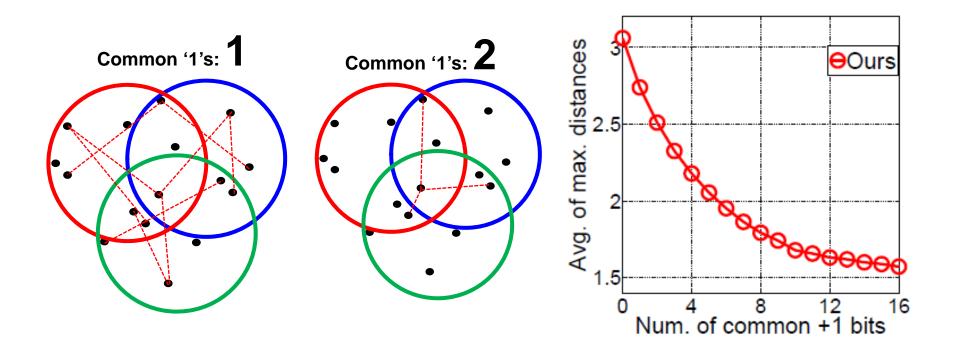


Max Distance and Common '1'





Max Distance and Common '1'



Average of maximum distances between two partitions: decreases as number of common '1'

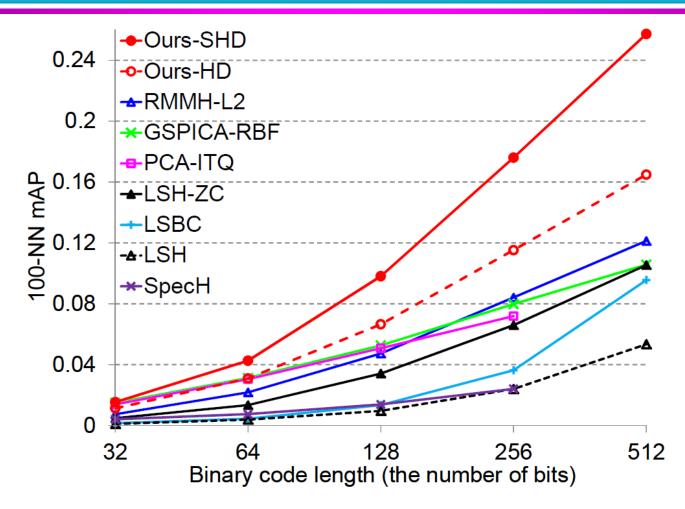
Spherical Hamming Distance (SHD)

$$d_{shd}(b_i, b_j) = \frac{|b_i \oplus b_j|}{|b_i \wedge b_j|}$$

SHD: Hamming Distance divided by the number of common '1's.



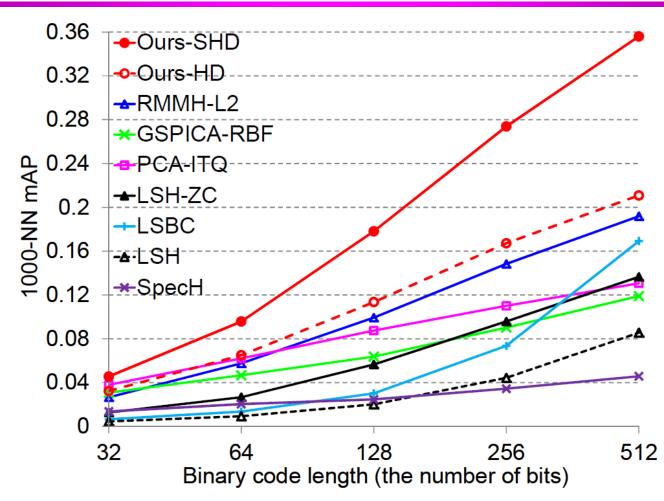
Results



384 dimensional 1 million GIST descriptors



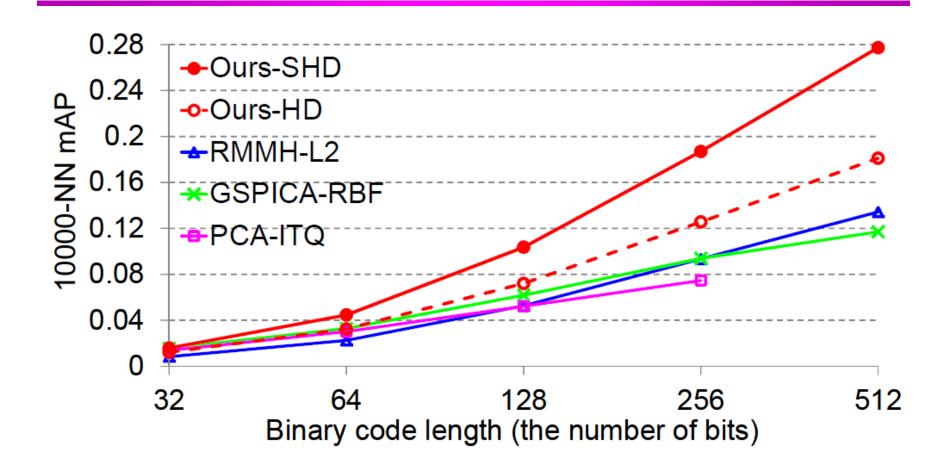
Results



960 dimensional 1 million GIST descriptors



Results



384 dimensional 75 million GIST descriptors



Summary

- The need of binary code embedding
- Spherical binary code embedding
 - Uses spherical hashing for tighter bounds
 - Iterative process to achieve balance and independence
 - Spherical Hamming distance

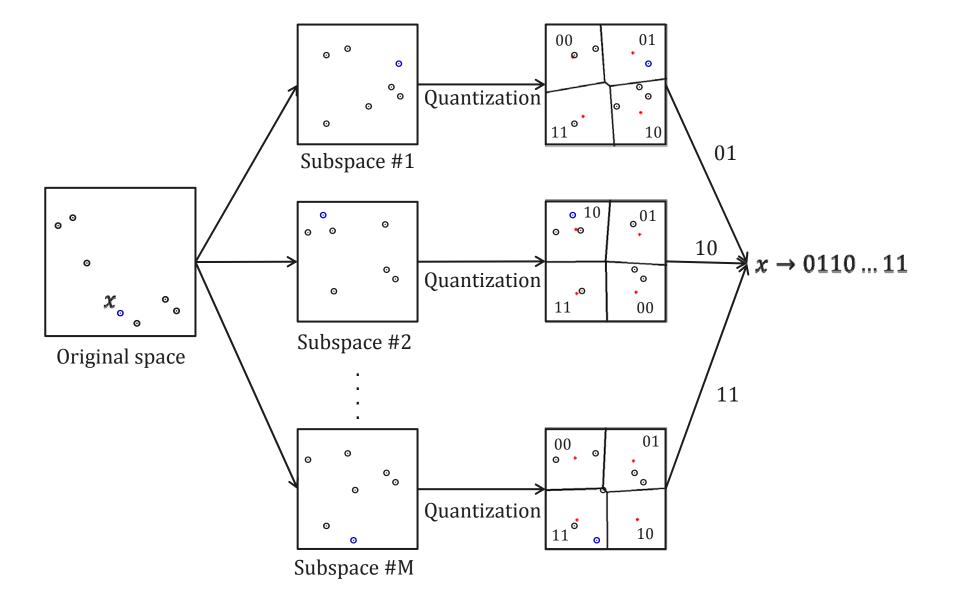


Distance Encoded Product Quantization

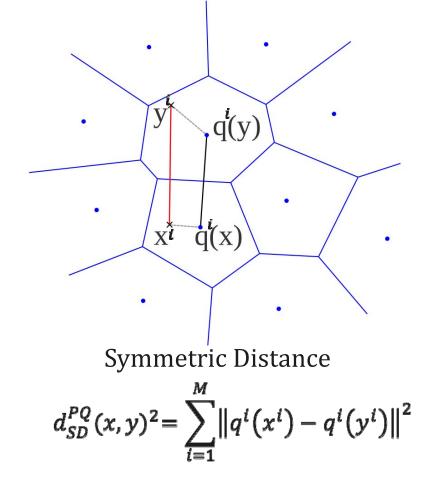
Jae-Pil Heo, Zhe Lin, and Sung-Eui Yoon

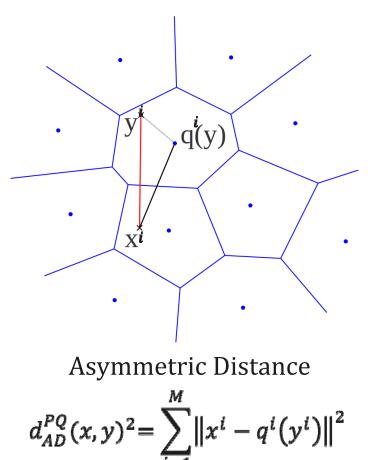
CVPR 2014

PQ: Product Quantization [Jegou et al., TPAMI 2011]



Distance Computation in PQ





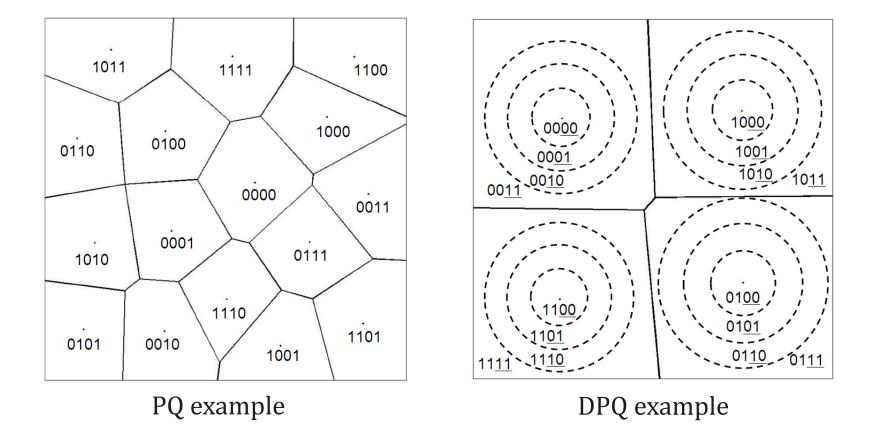
Terms

x: query, y: data, M: # of Subspaces, q^i : quantizer in i^{th} subspace, x^i : sub-vector of x in i^{th} subspace

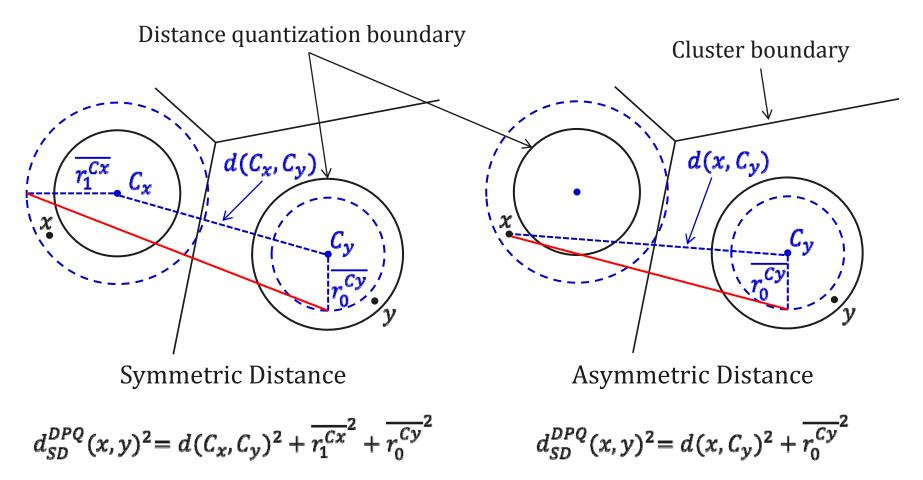
Figures are from [Jegou et al., TPAMI 2011]

DPQ: Distance Encoded PQ

• DPQ encodes quantized distance from the center as well as the cluster index in each subspace.

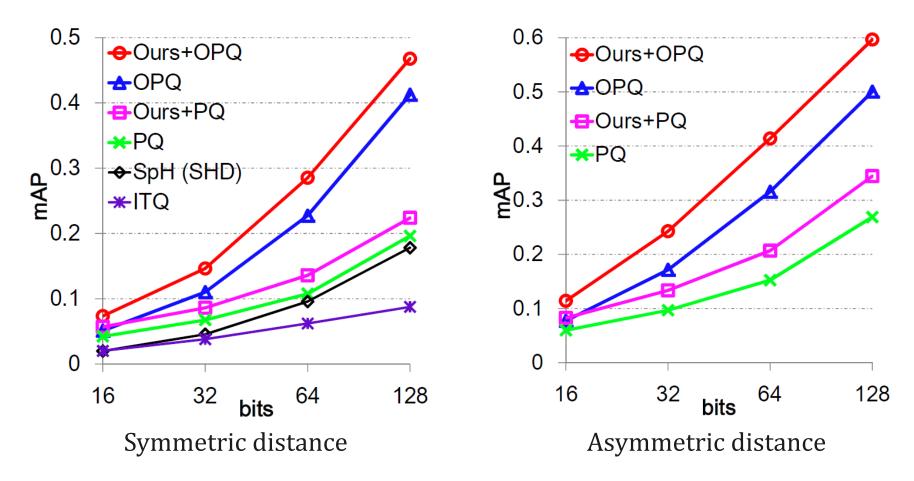


Distance Computation in DPQ



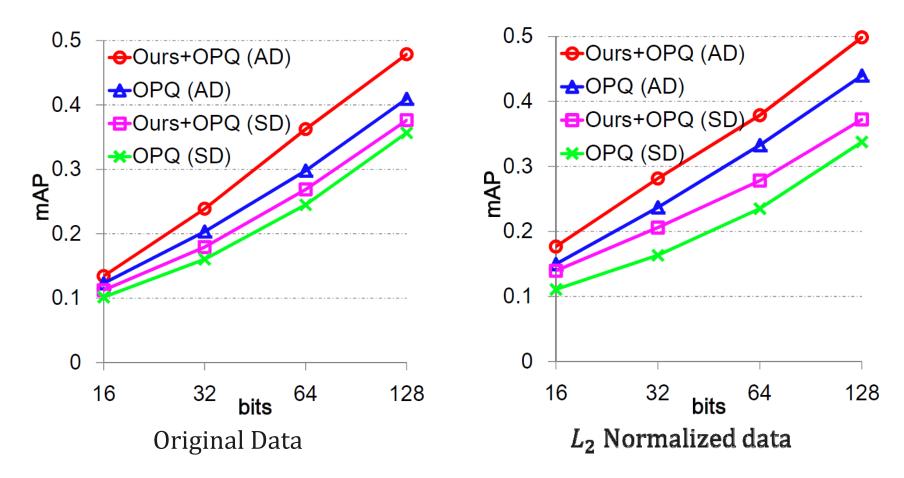
 $\overline{r_j^C}$: average distance from the center to points whose cluster center is C and quantized distance index is j

Results on GIST-1M-960D



1000-nearest neighbor search mAP OPQ: Optimized PQ [Ge et al., CVPR 2013] SpH: Sperical Hashing [Heo et al., CVPR 2012] ITQ: Iterative Quantization [Gong and Lazebnik, CVPR 2011]

Results on BoW-1M-1024D



1000-nearest neighbor search mAP SD: Symmetric distance AD: Asymmetric distance

Conclusions

• Visual data are exploding!

- Image search is one of key techniques for various application including classification
- Processing them requires scalable algorithms
 - Hashing techniques for nearest neighbor search
- Codes are available

http://sglab.kaist.ac.kr/software.htm

